



# Performance Analysis and Data Processing for the High Solidity Test Campaign in the Jet Propulsion Laboratory 25-ft Space Simulator

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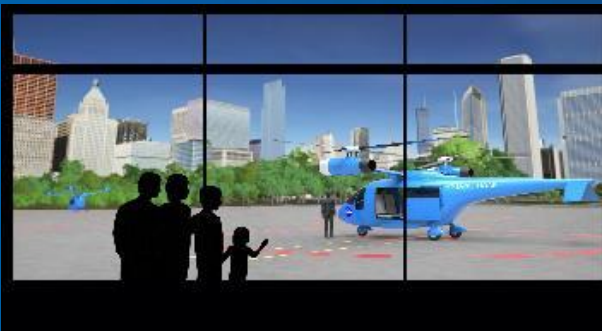
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**VFS Forum 82**  
**West Palm Beach, FL**  
**May 7, 2026**



- Background
- Experimental Test Campaigns
- Motivation
- Test Objectives and Impact
- Test Set Up
  - Facility
  - Hardware
  - Conditions
  - Test Matrix
- Data Collection and Processing
- Results
- Summary and Conclusions

# Background



## **Ingenuity** (2015 – 2024)

- First flew on Mars in 2021
- Flight technology demonstrator

## **Sample Recovery Helicopter (SRH)** (2022 – 2024)

- Conceptual design for recovering sample tubes

## **Rotor Optimization for the Advancement of Mars eXploration (ROAMX)** (2020 – 2025)

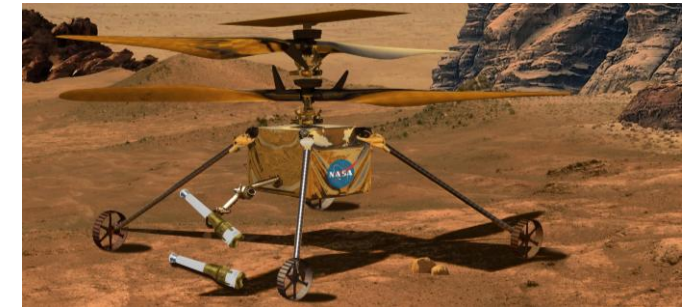
- Advanced Mars rotor design using optimization tool

## **Higher Payload Concept Vehicles** (2019 – 2025)

- Mars Science Helicopter (MSH)
- Chopper



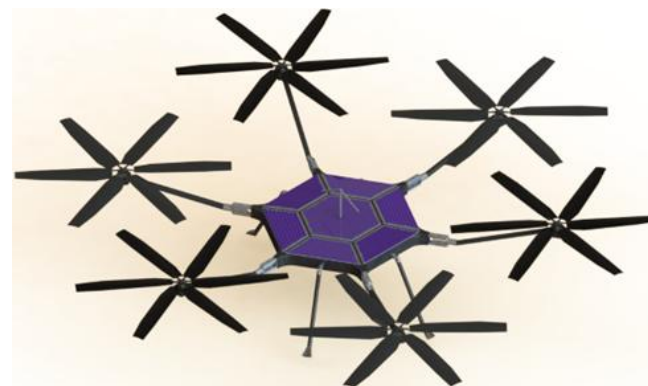
*Ingenuity*



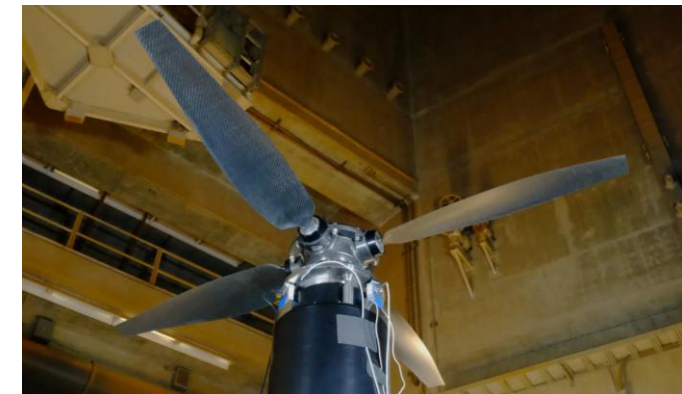
*SRH*



*Chopper*



*MSH*



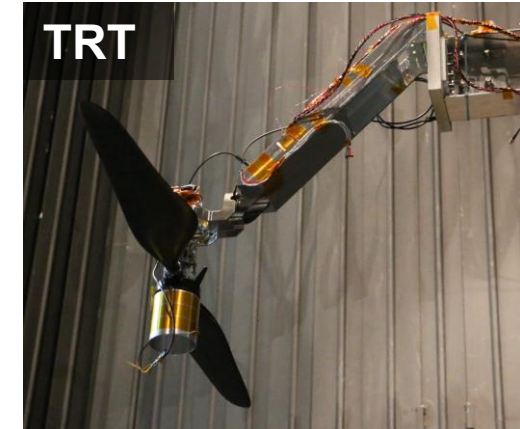
*ROAMX*

# Experimental Test Campaigns



## Engineering Development Model- (EDM-1) and Transonic Rotor Test (TRT)

- Ingenuity rotor to see how much lift can get, in anticipation of Sample Return Helicopter (SRH)
- Increase in collective pitch and RPM



## Dual Rotor Test (DRT) for SRH

- Model used to assess performance gains with redesigned rotor blade (increased area and optimized planform/twist) to meet SRH lift requirements



## High Solidity Test (HST)

- Chopper (with ROAMX airfoils), to see effect of high solidity



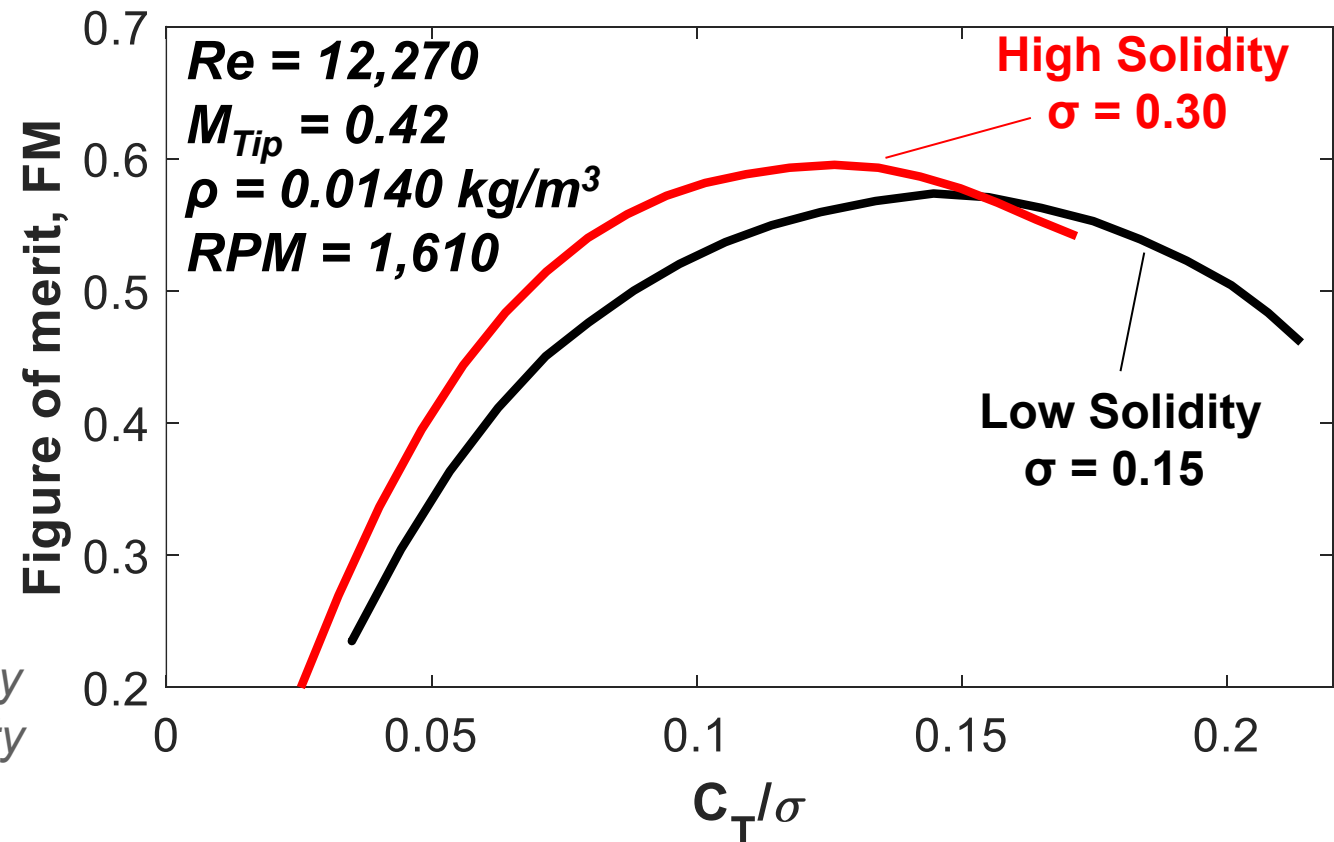
# Motivation for High Solidity Test (HST)



- Rotor designs typically have solidities ( $\sigma$ ) of  $\sim 0.04 - 0.15$
- Future Mars missions will require increased payload/range/endurance for a fixed size, therefore **more lift needed** (*Example: Mars Science Helicopter and Chopper*)
- More blade area gives thrust **and** better efficiency
  - **High rotor solidity** (different planform and blade number) affects performance as measured by FM vs  $C_T/\sigma$



## CAMRAD II predictions for HST rotors



*Aircraft Design I, Technical Session C: Wednesday at 2:15 PM - 2:45 PM "Optimization of High Solidity Rotor Performance in a Martian Environment"*

# Test Objectives and Impact



**Mars Exploration Program (MEP) funded a joint test campaign between NASA's Jet Propulsion Laboratory, NASA Ames Research Center, and AeroVironment, Inc. to validate performance predictions for low- and high-solidity rotor variants at Mars pressures.**

## **Objectives**

Characterize the performance of increased thrust-weighted solidity

1. Low solidity (3-blades)
2. High solidity (6-blades)

**Results will aid in future Mars rotorcraft development by providing data for validation efforts**

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# Testing Facility



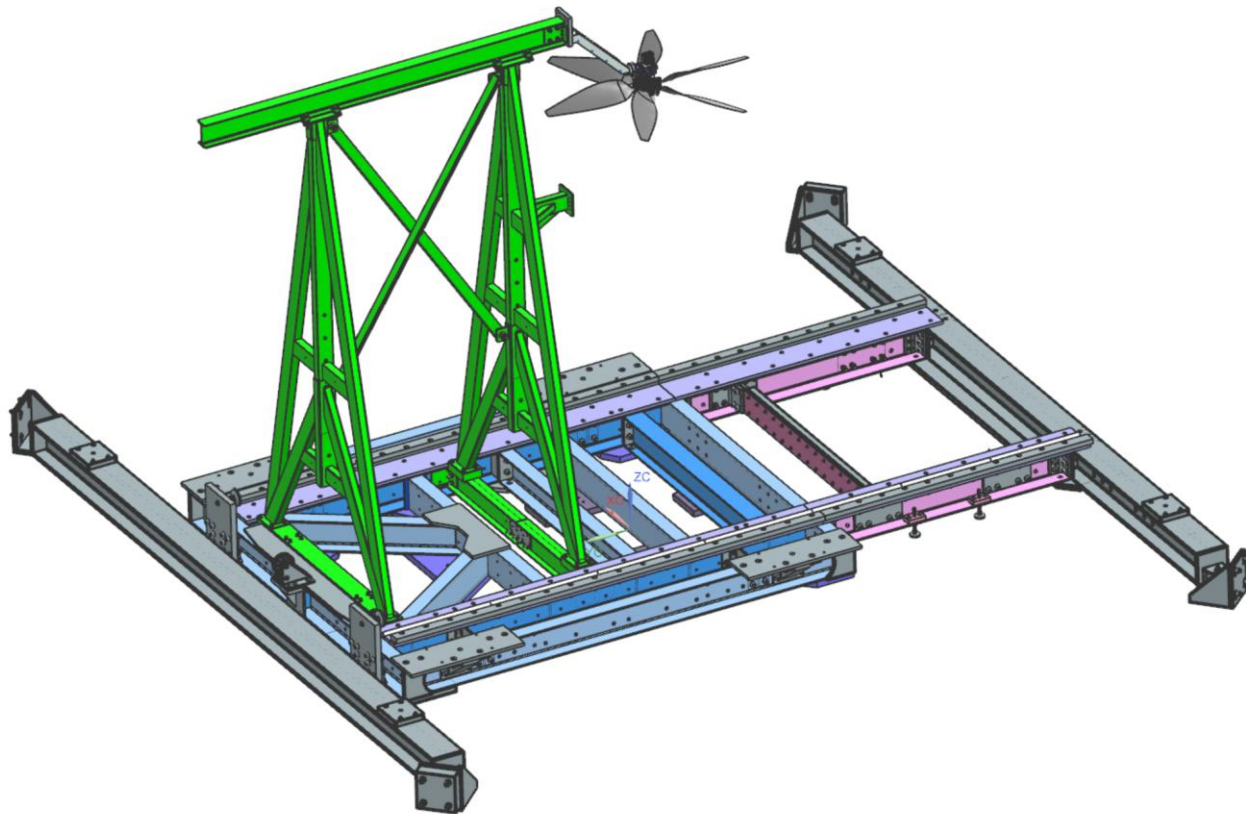
- 25-ft Space Simulator located at NASA's Jet Propulsion Laboratory
  - Evacuated of all air and then backfilled with CO<sub>2</sub> to the target density
  - Temperature not controlled for this test (19 – 27 degrees Celsius)



# Test setup



- Low and high solidity test articles mounted in the 25-ft Space Simulator
- Test articles supported on gantry
- Instrumentation included force/torque sensor, 4 cameras, microphone, and accelerometers



# Rotor geometry



|                            | <b>Ingenuity</b> | <b>SRH</b> | <b>ROAMX</b> | <b>HST</b>      |
|----------------------------|------------------|------------|--------------|-----------------|
| Total number of blades     | 4                | 4          | 4            | 3 and 6         |
| Radius (m)                 | 0.605            | 0.706      | 0.720        | 0.675           |
| Chord (75%R) (m)           | 0.0740           | 0.0700     | 0.10         | 0.1167          |
| $\sigma$ (thrust-weighted) | 0.148            | 0.126      | 0.167        | 0.150 and 0.300 |
| Outboard airfoil           | CLF5605          | CLF5605    | roamx-0201   | 2.5% t/c ROAMX  |

- High solidity is a result of increased number of blades and chord distribution



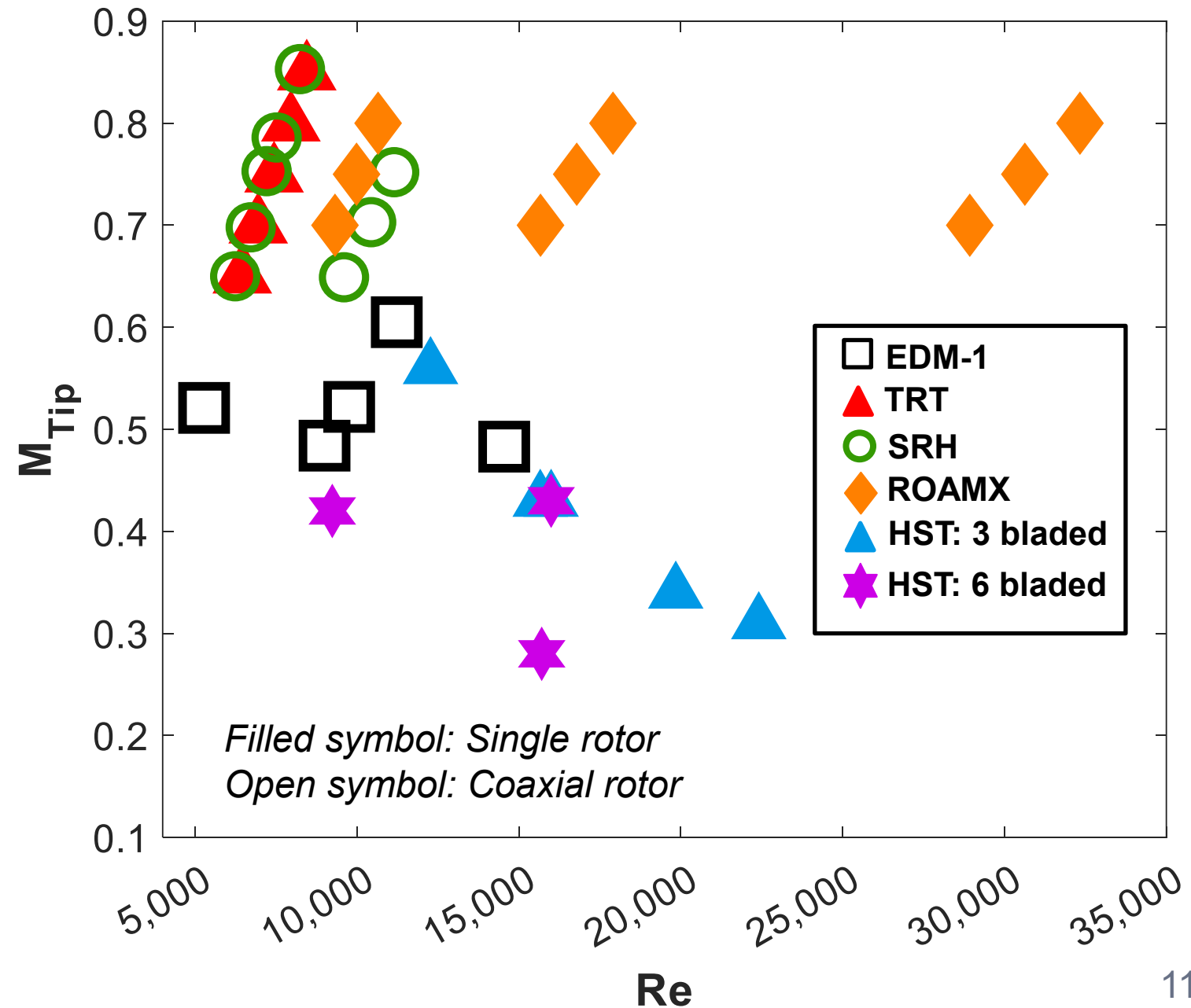
# Test Conditions



- Previous test conditions were set to simulate the densities at Jezero Crater rim and lower

$$Re = \frac{\rho V_{.75} C_{.75}}{\mu}$$

- Additional conditions for HST included higher Reynolds number due to the increased chord and density variation



| Rotor system | Density (kg/m <sup>3</sup> ) | M <sub>Tip</sub> | Reynolds number |
|--------------|------------------------------|------------------|-----------------|
| 3            | 0.014                        | 0.56             | 12,270          |
|              | 0.023                        | 0.43             | 15,660          |
|              | 0.024                        | 0.43             | 16,000          |
|              | 0.038                        | 0.34             | 19,850          |
|              | 0.047                        | 0.31             | 22,410          |
| 6            | 0.014                        | 0.42             | 9,240           |
|              | 0.036                        | 0.28             | 15,710          |
|              | 0.024                        | 0.43             | 16,000          |

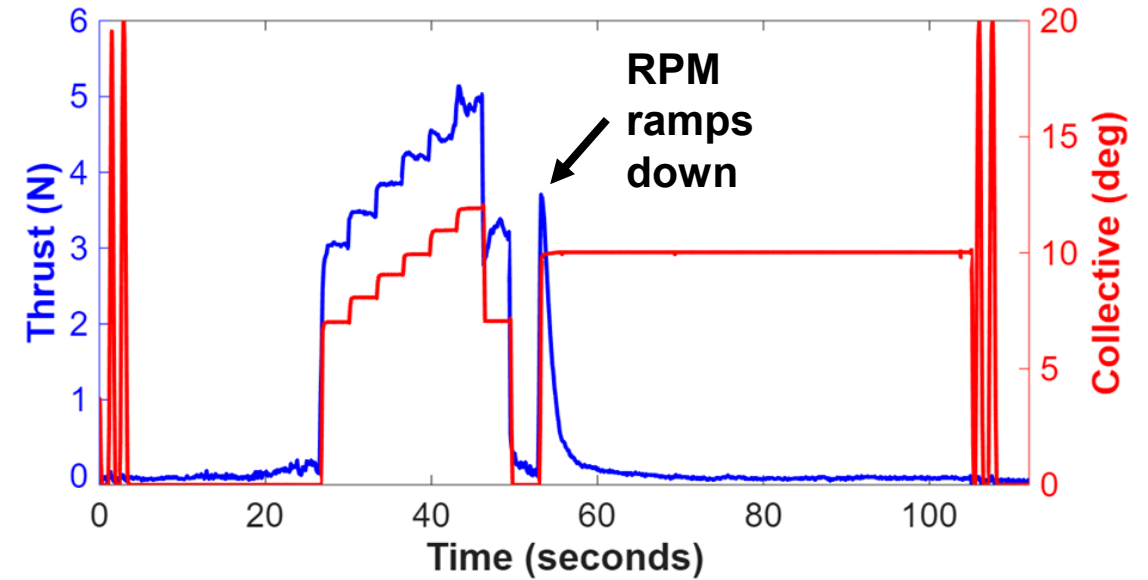
- To get higher Reynolds number the density was increased without increasing M<sub>tip</sub>
- Low M<sub>Tip</sub>, no compressibility/shock effects

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# Data Collection and Safety Monitoring



- Each run lasted no more than ~60 seconds due to motor heating limitations
- Data collected on multiple systems
  - Helicopter control (RPM and **collective**)
  - Force/torque (**thrust**/power)
  - Accelerometers
- Safety and diagnostic monitoring
  - Microphone
  - **Video**



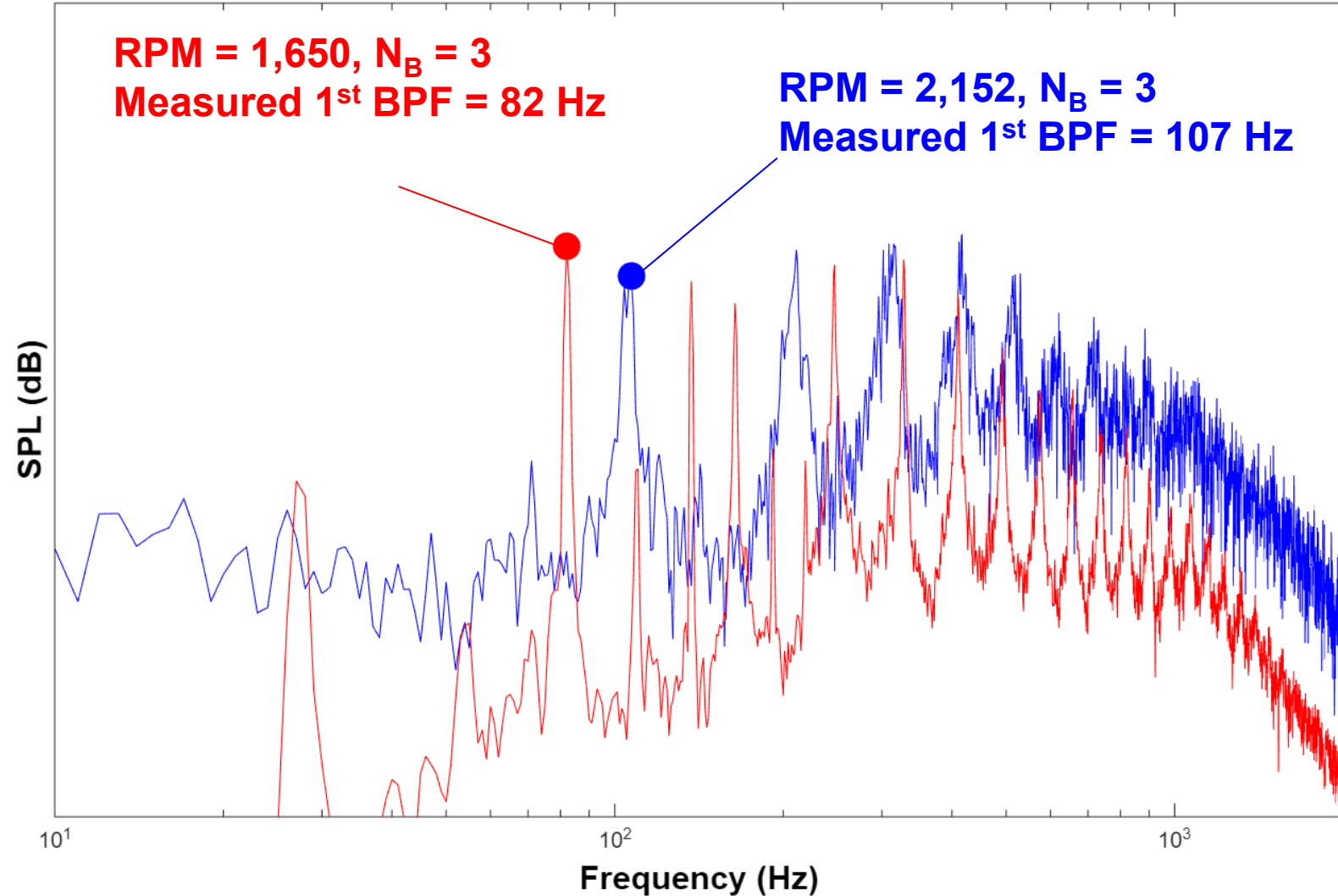
# Safety Monitoring: Microphone



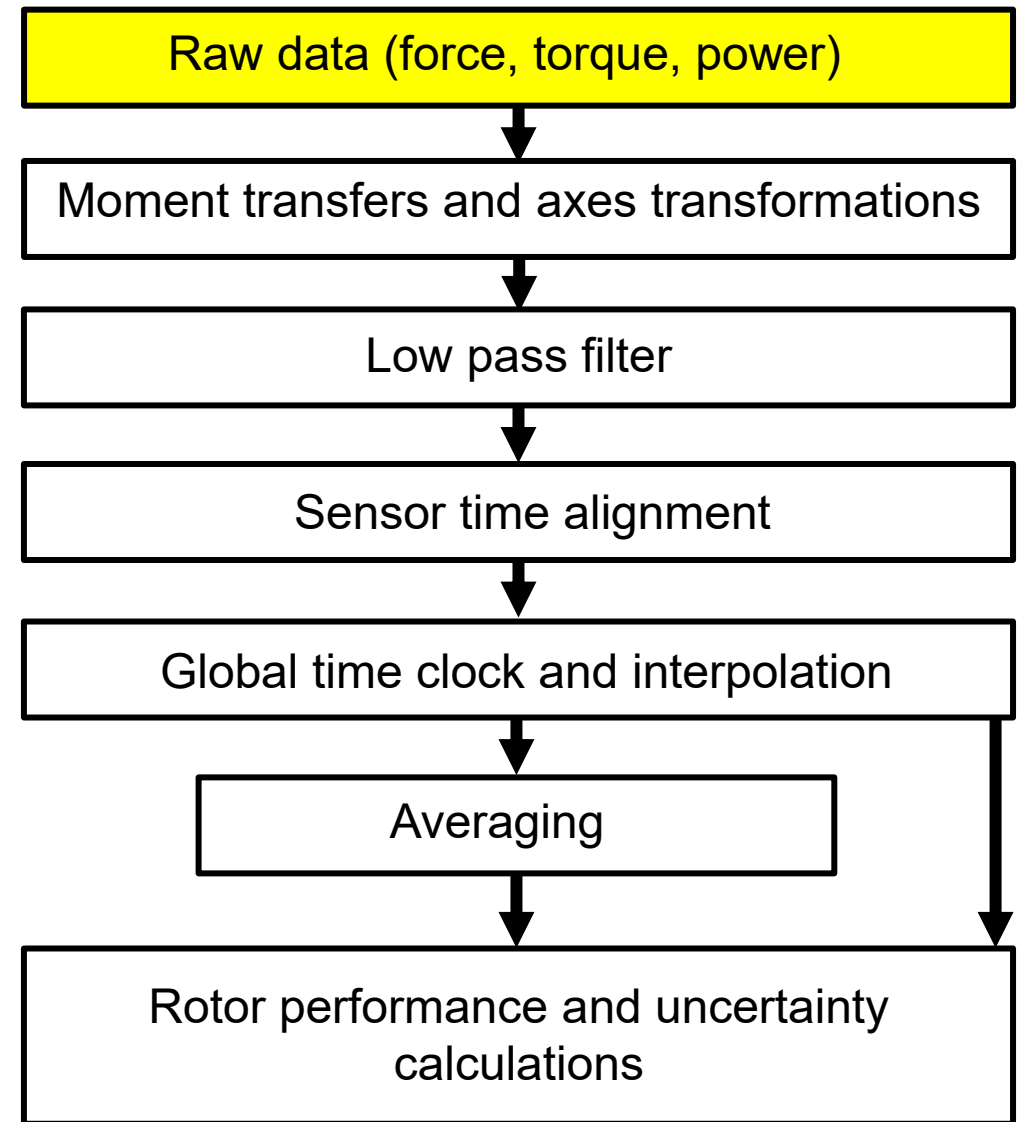
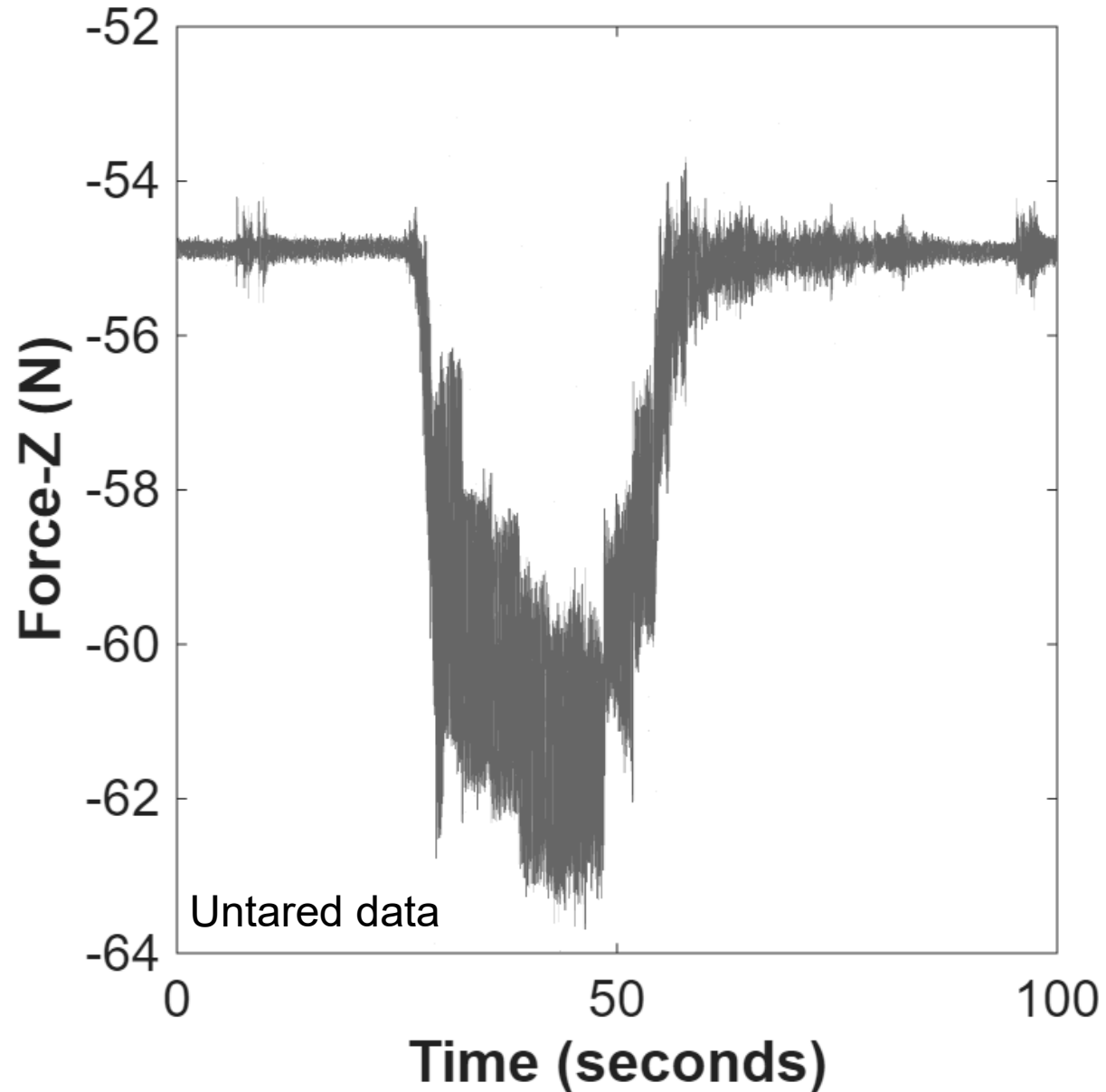
- Single microphone installed beneath rotor for safety monitoring
- Acoustic spectra of measurements processed and used to identify and validate RPM through blade pass frequency (BPF)

$$BPF (Hz) = \frac{RPM * N_B}{60}$$

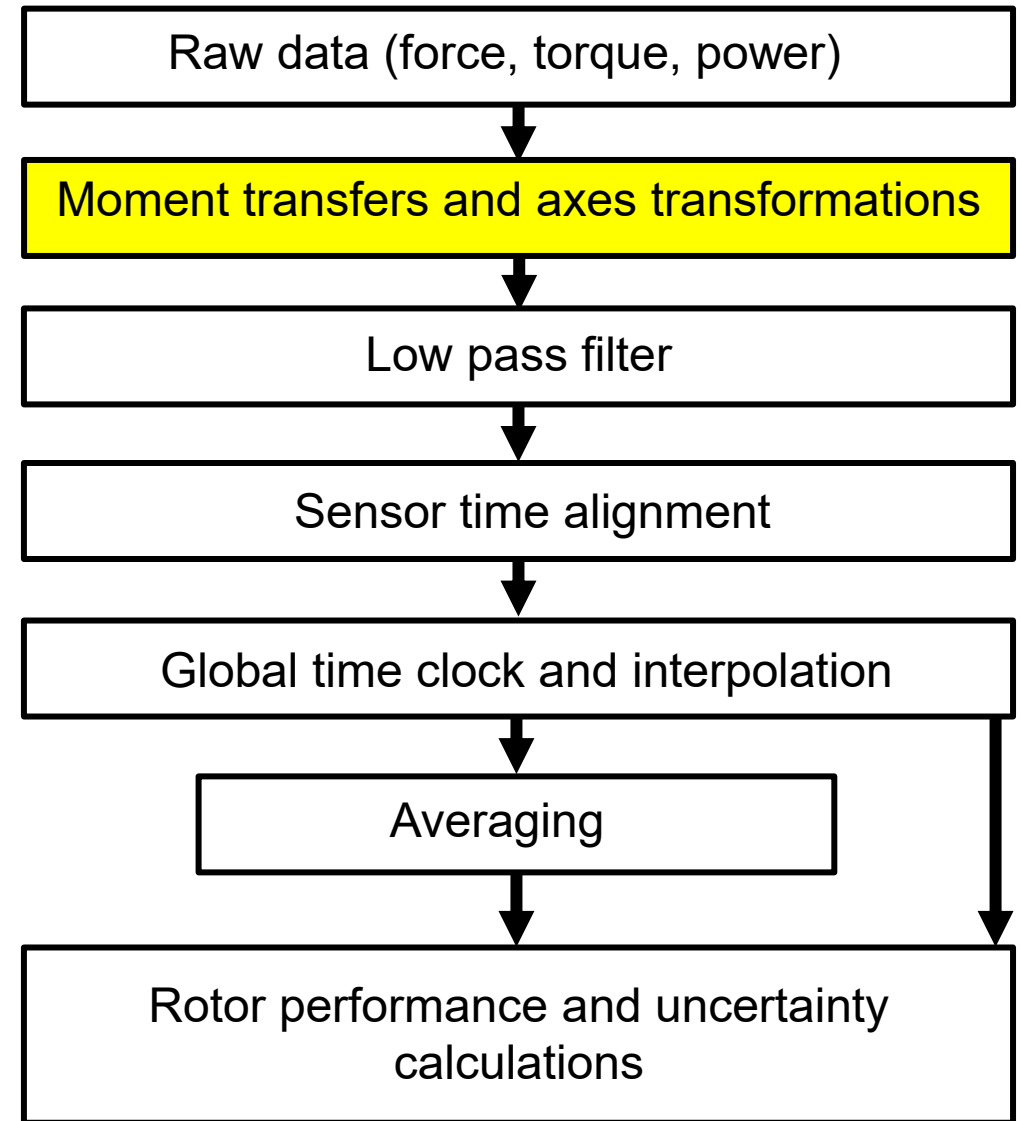
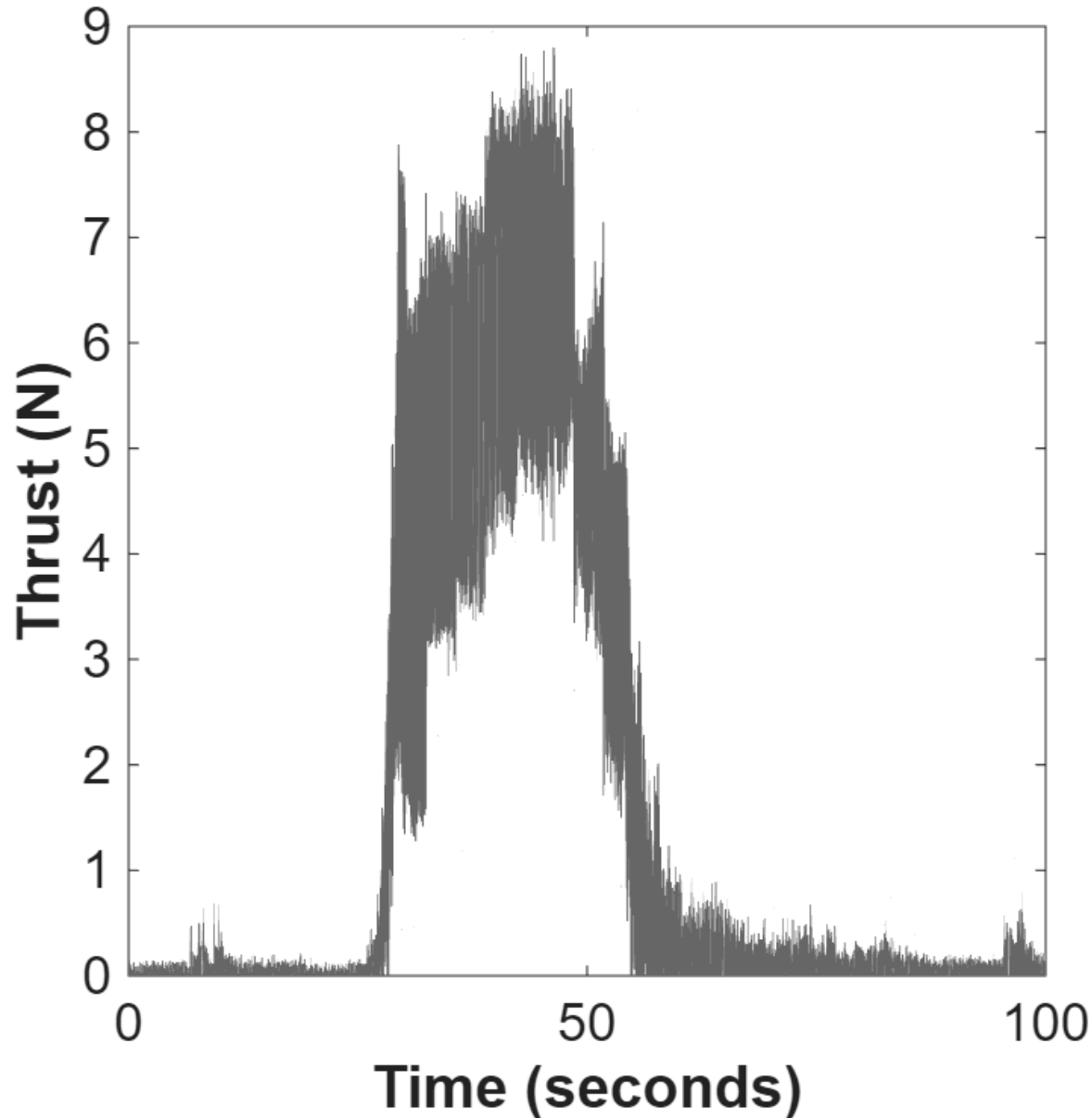
$N_B$  = Number of blades



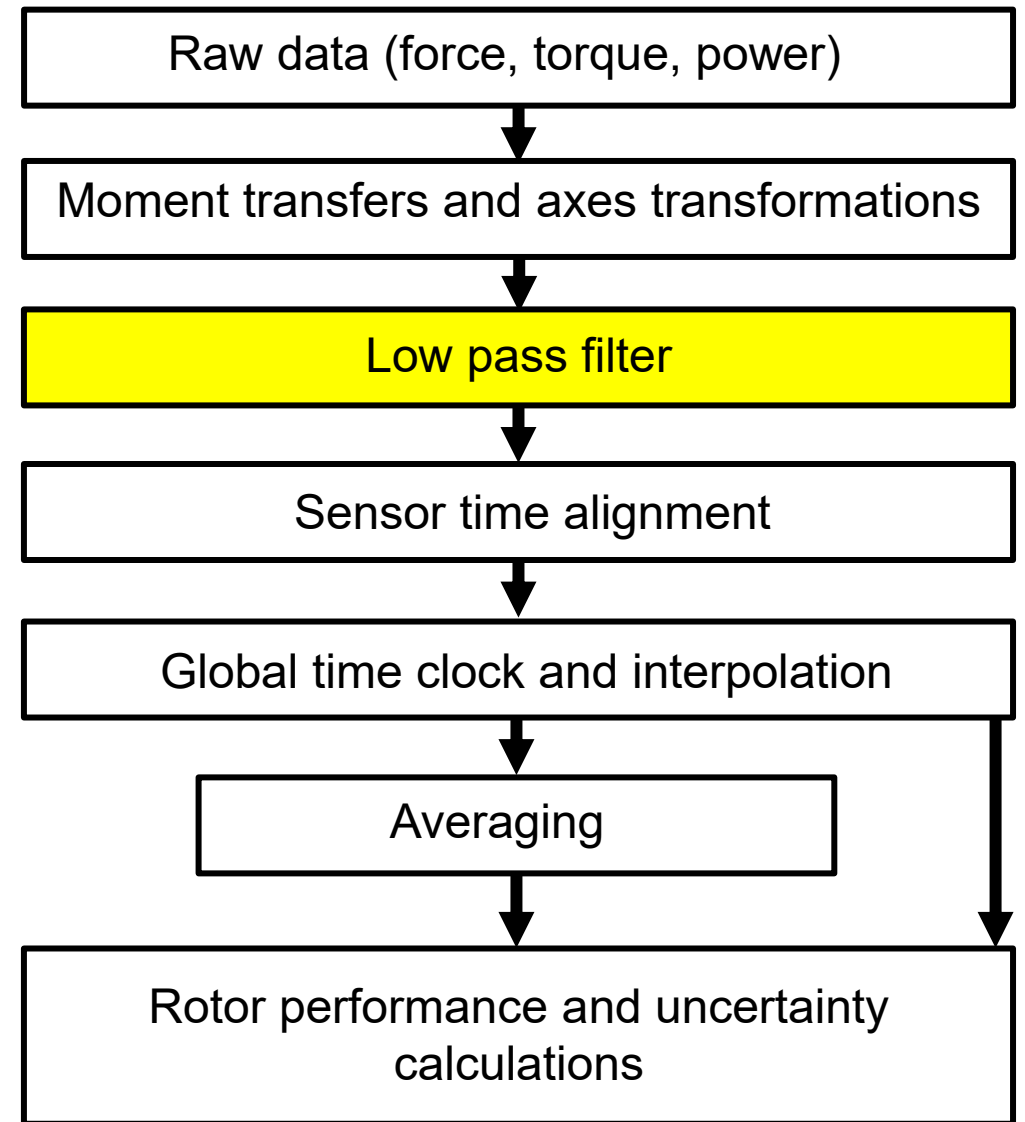
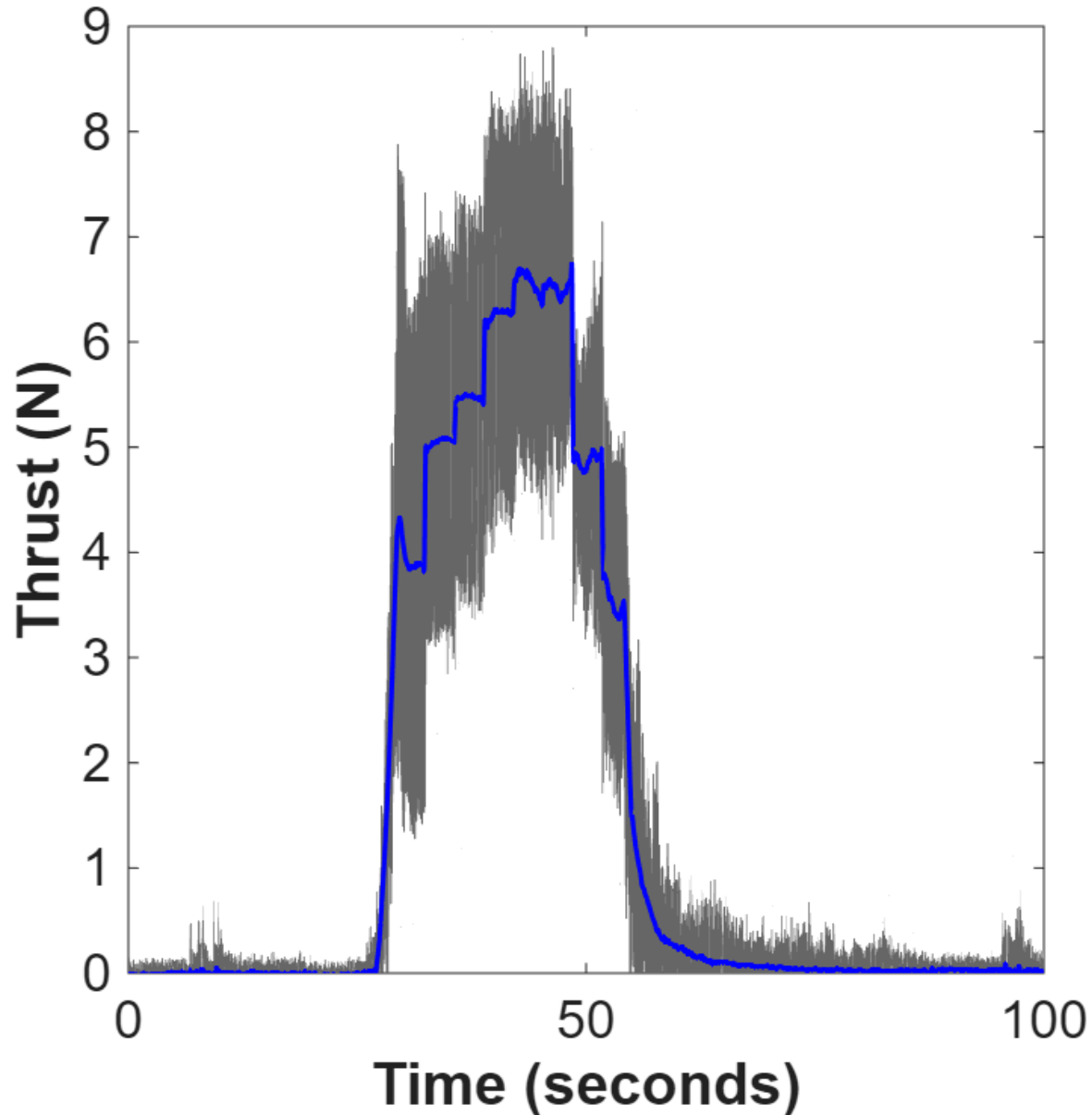
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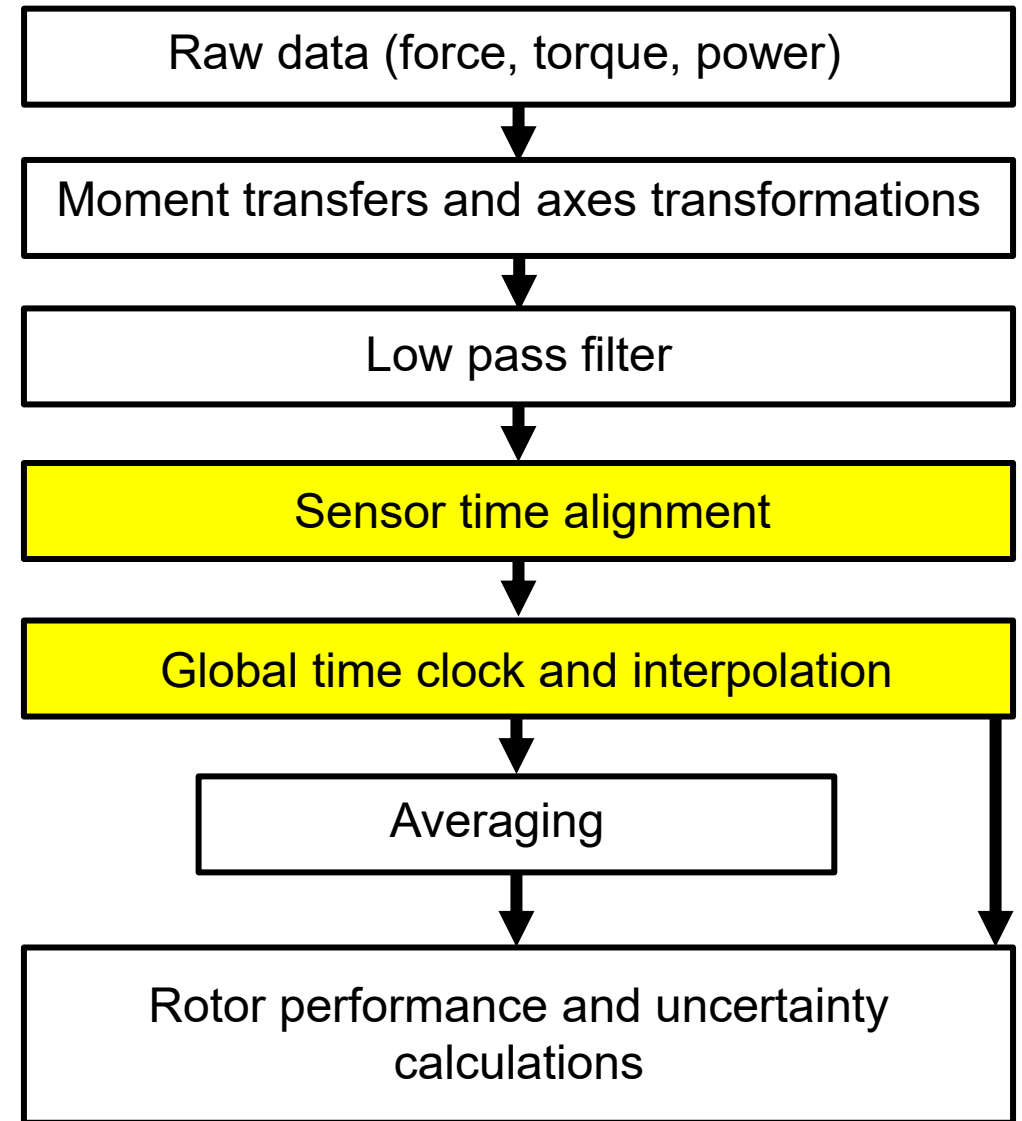
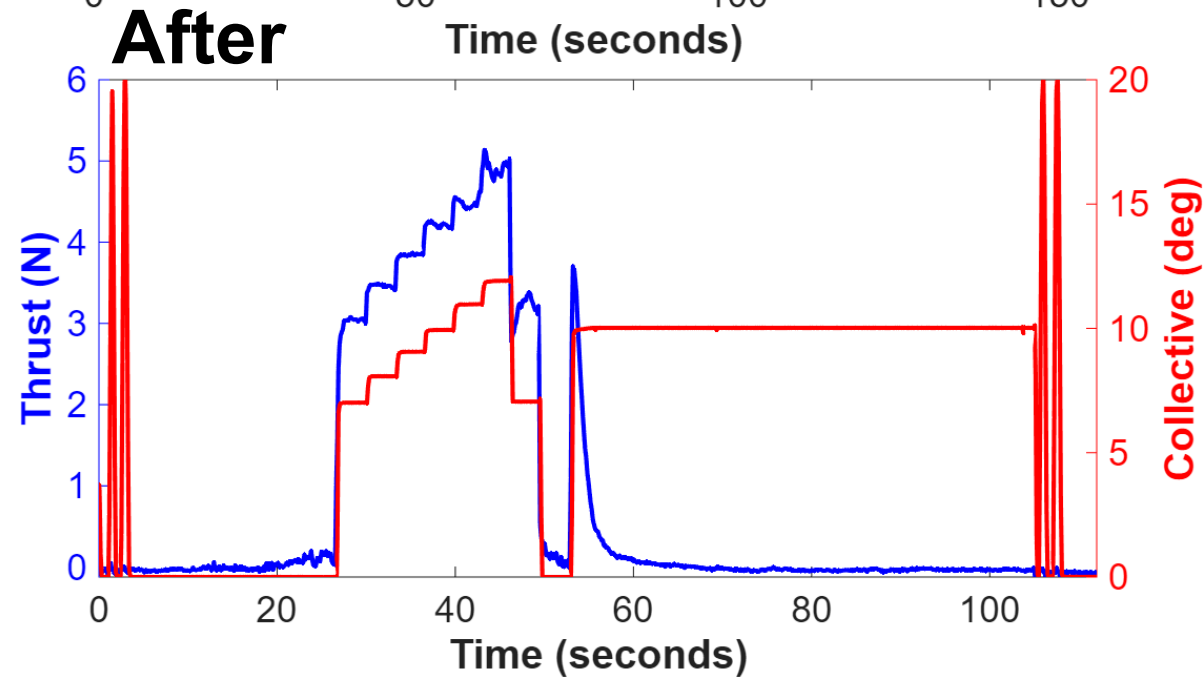
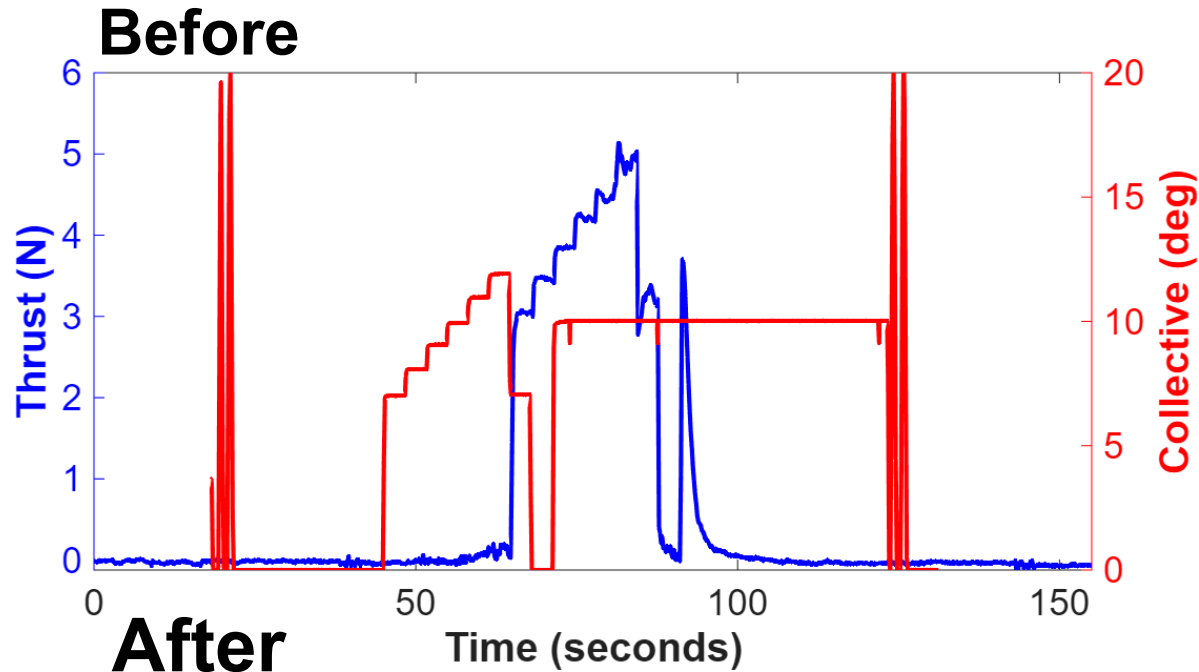
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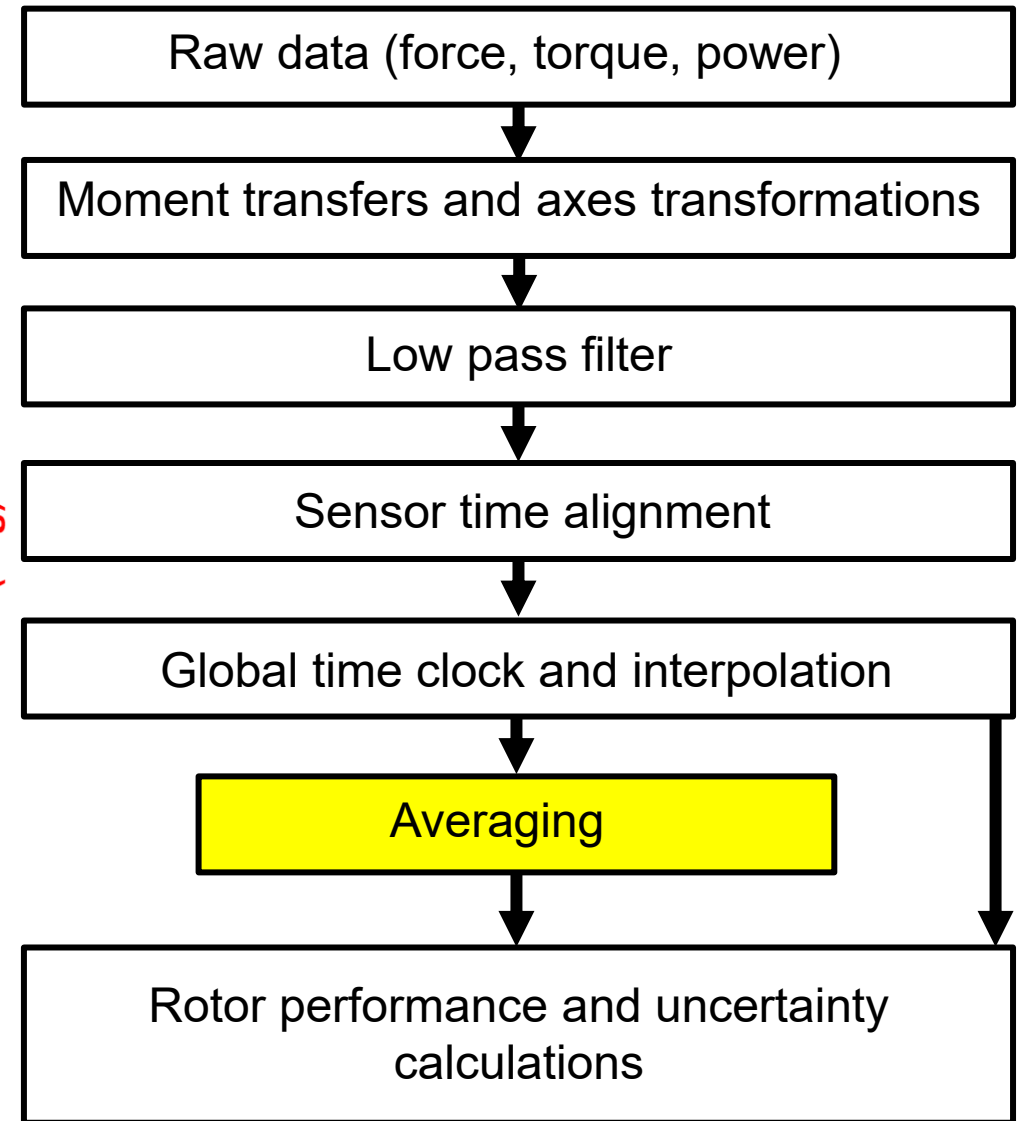
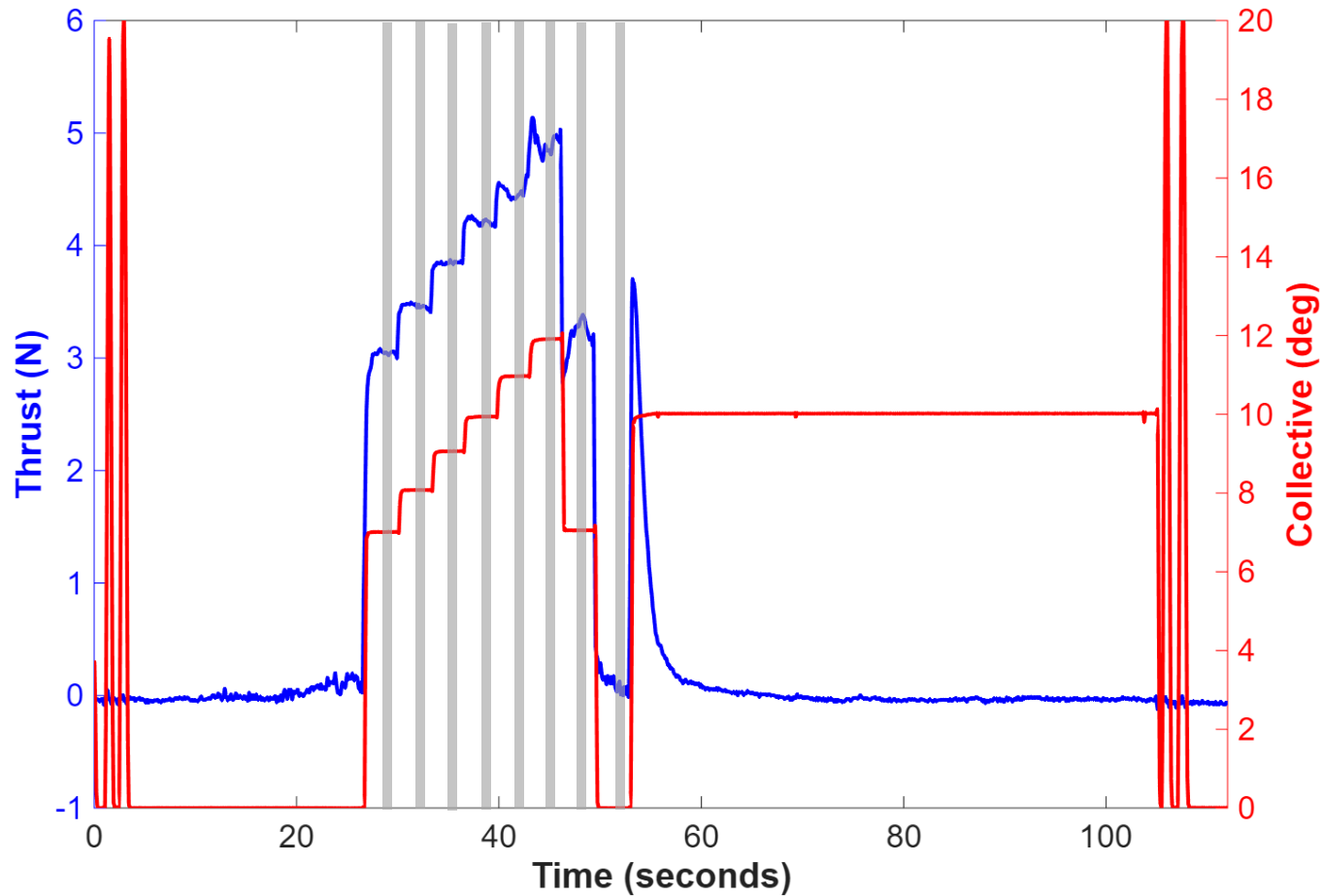
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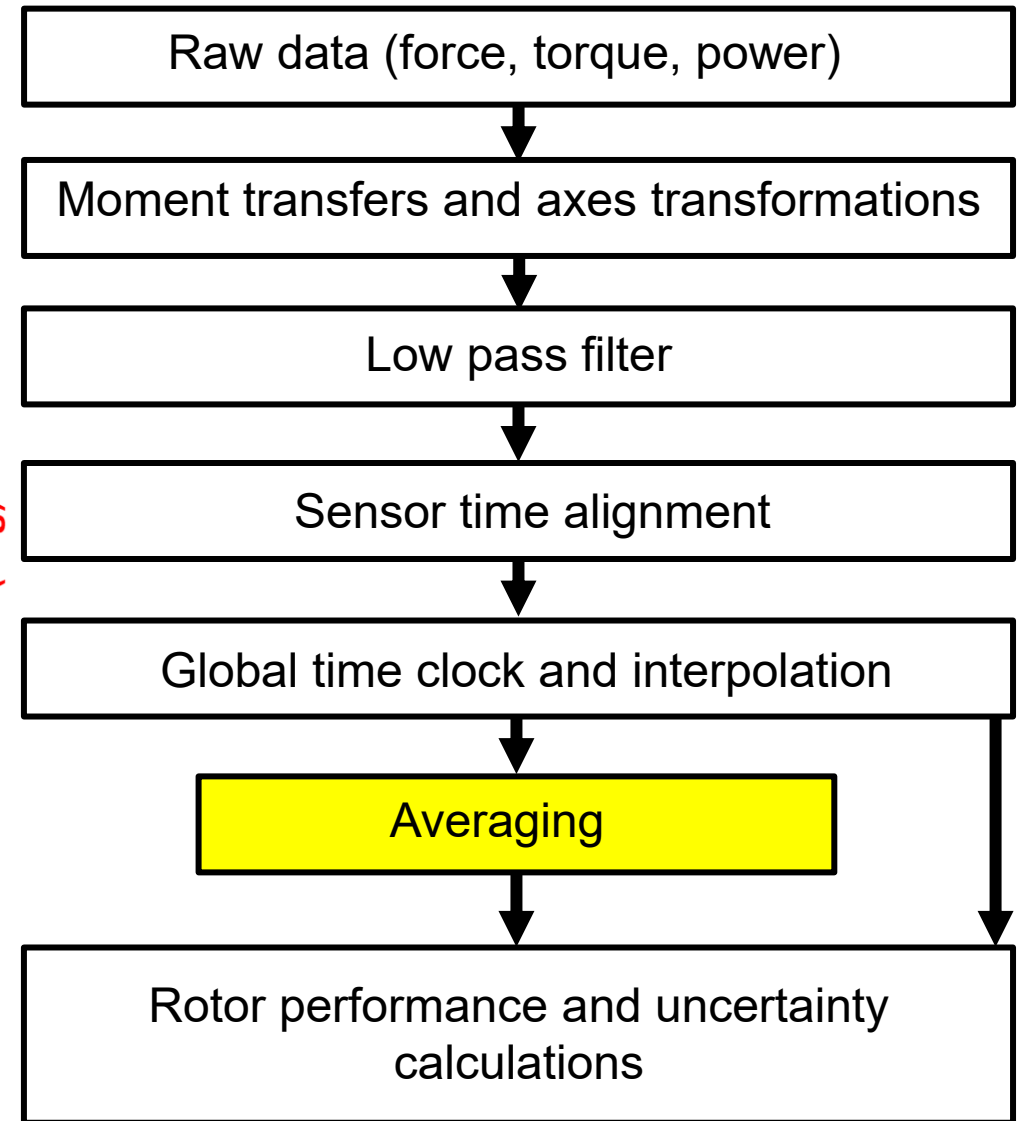
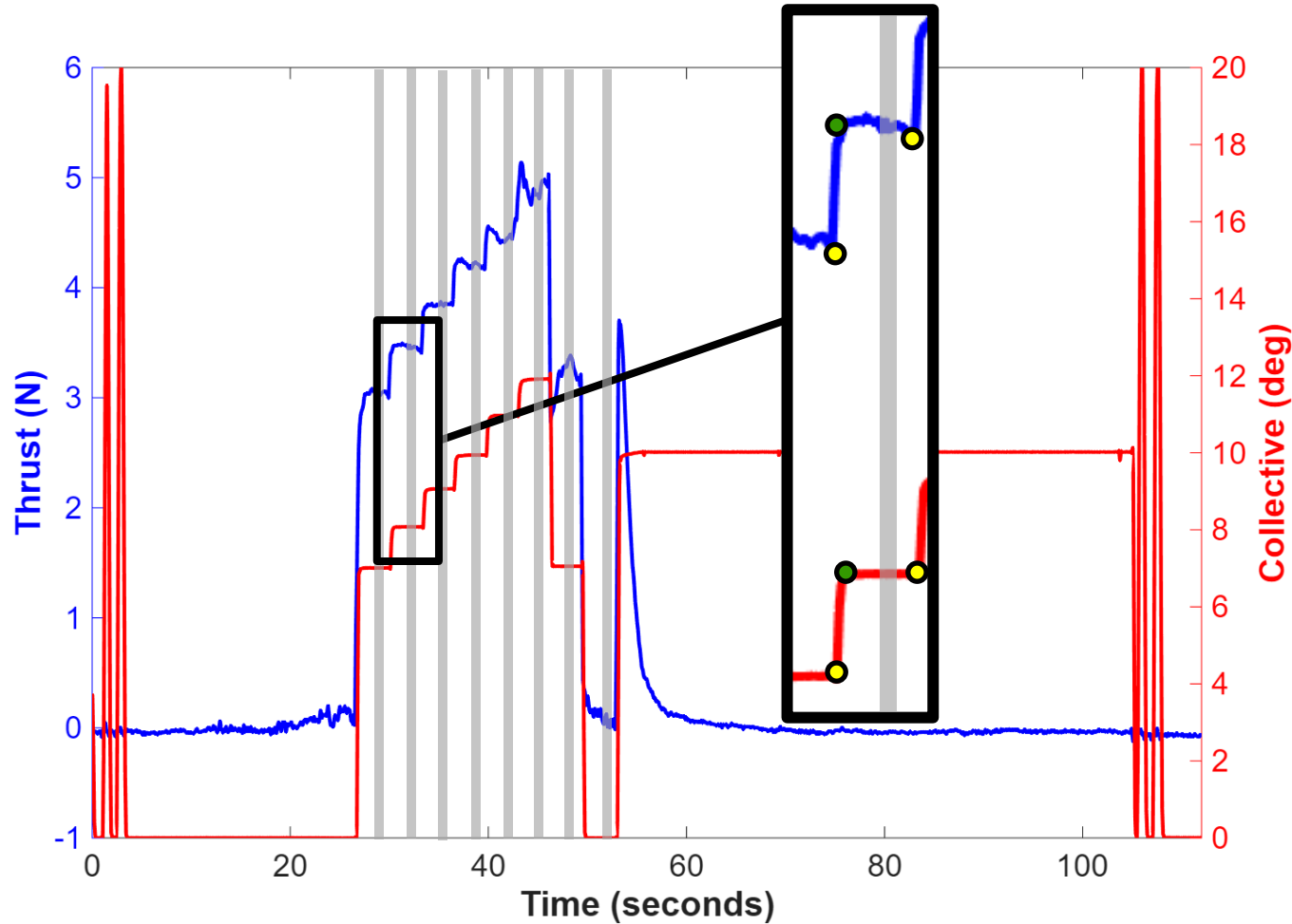
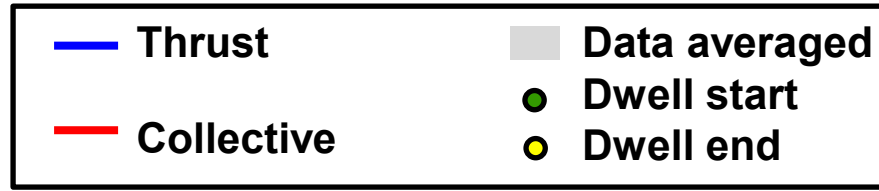
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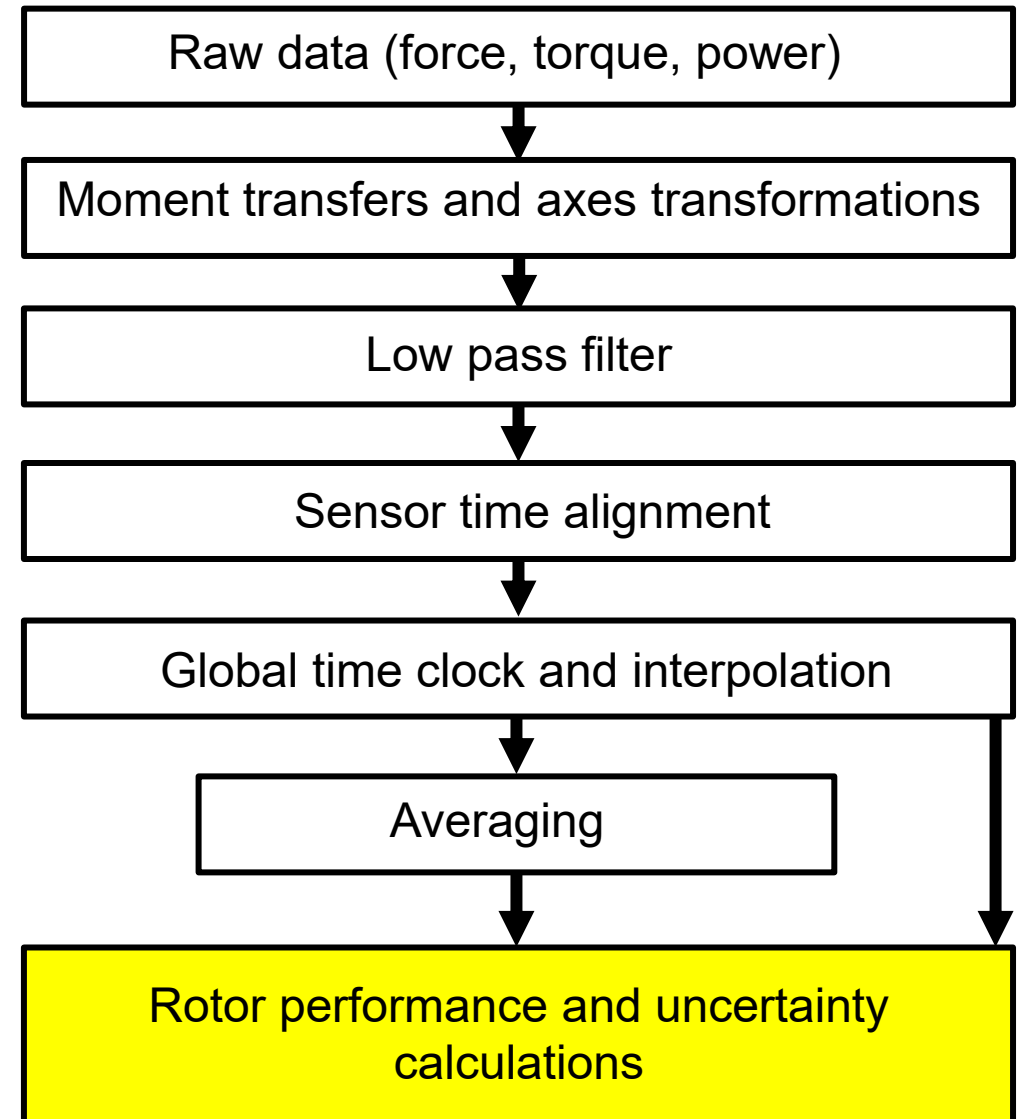
# Data Processing



$$C_T = \frac{T}{\rho A (\Omega R)^2}$$

$$C_P = \frac{P}{\rho A (\Omega R)^3}$$

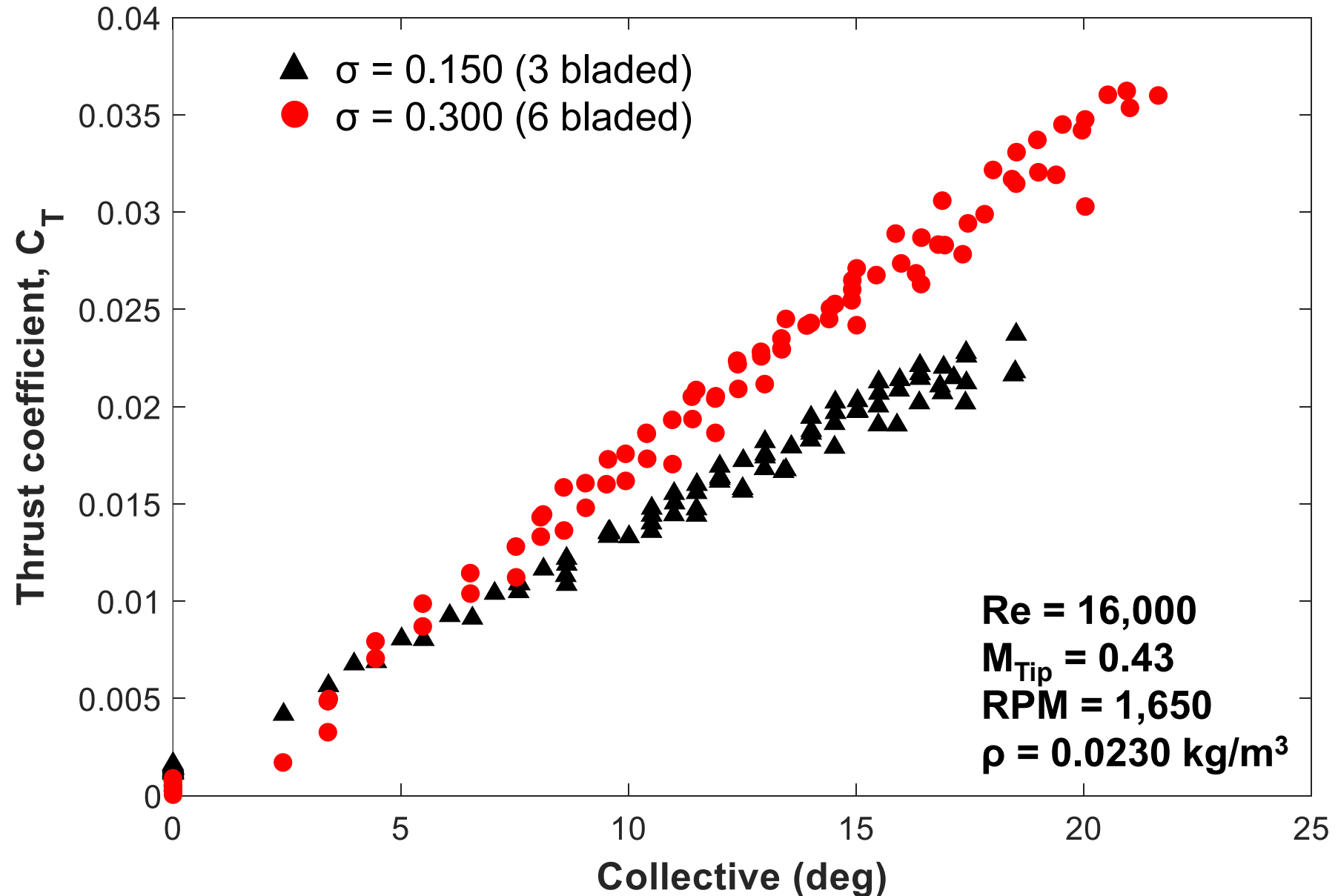
$$FM = \frac{C_T^{3/2}}{\sqrt{2} C_P}$$



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# Results: $C_T$ vs Collective (Low versus High Solidity)

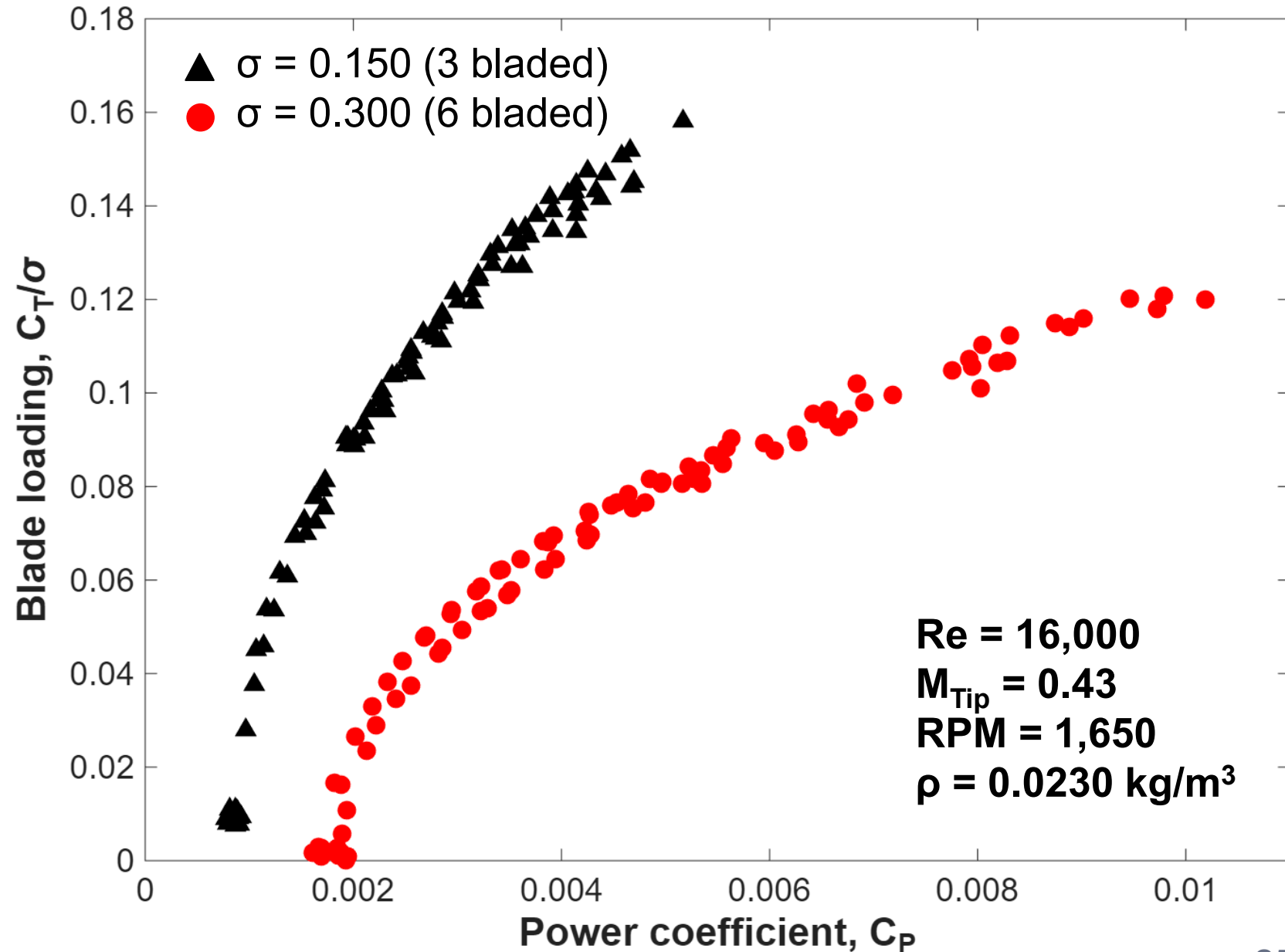
- More thrust capability with increase in solidity (number of blades)



# Results: $C_T/\sigma$ versus $C_P$ (Low versus High Solidity)



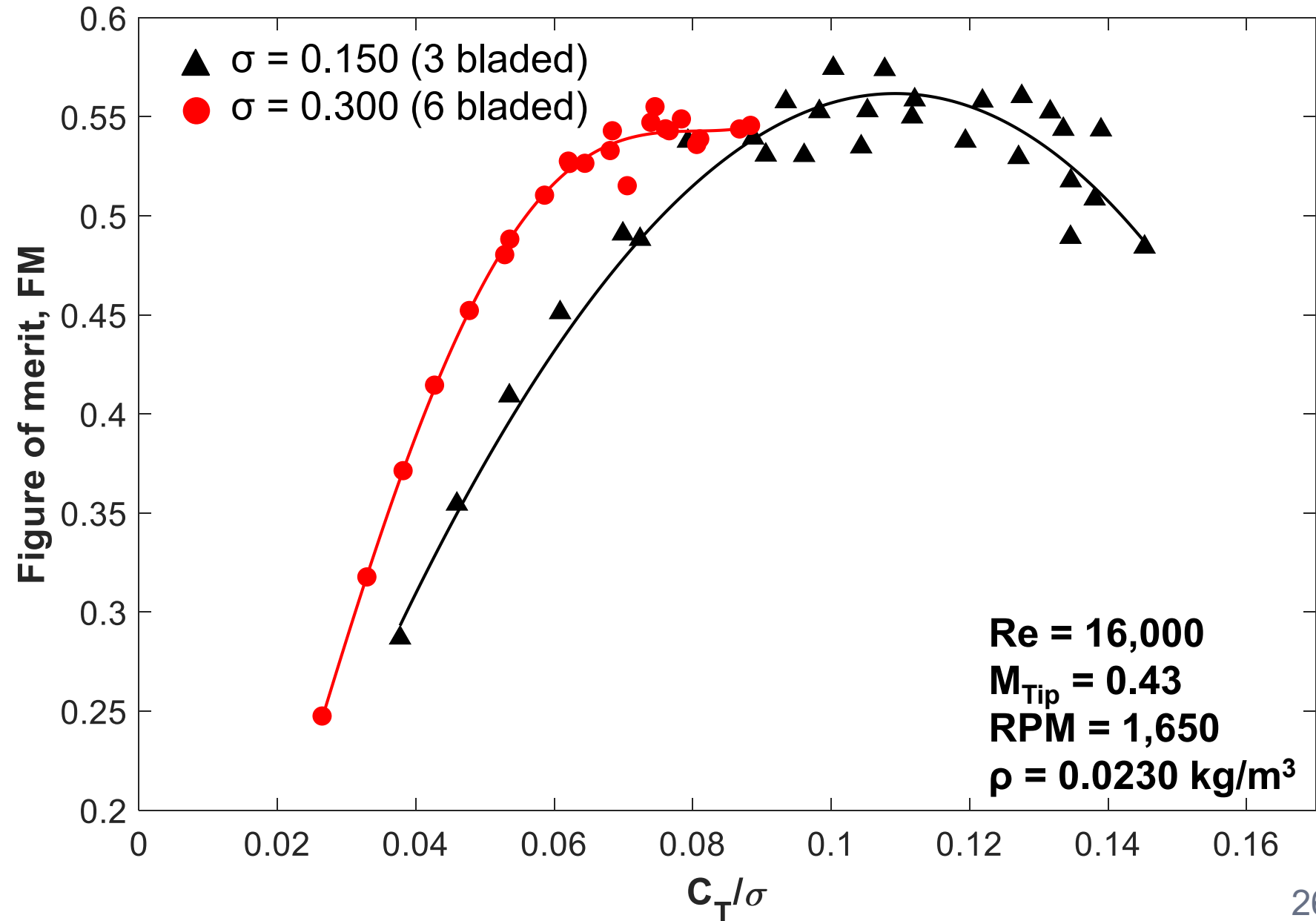
- Increase in solidity therefore increase in profile power
- More blades, higher chance of blade vortex interaction



# Results: FM vs $C_T/\sigma$ (Low versus High Solidity)



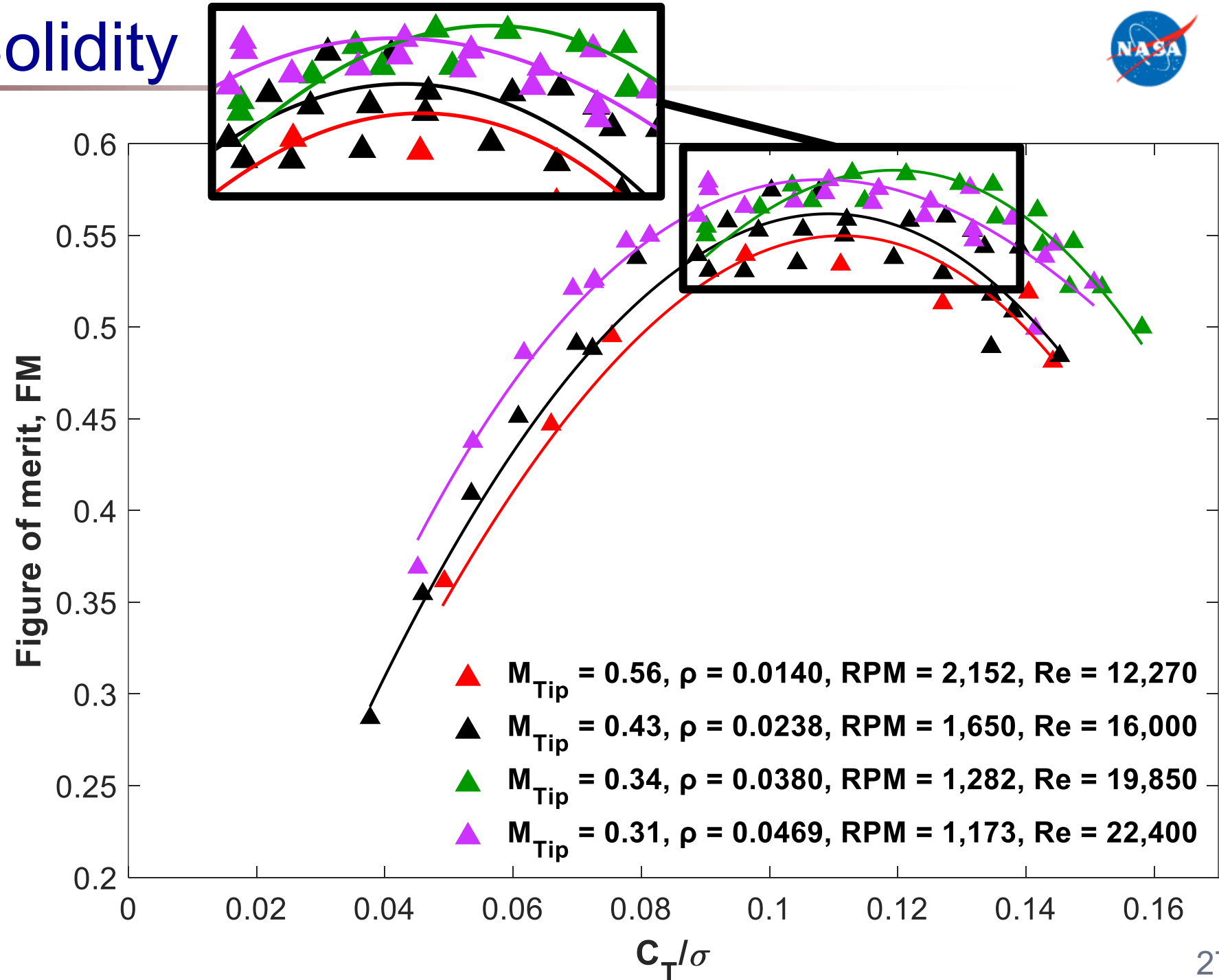
- Figure of merit (FM) shown to highlight efficiency of rotors
- 3-bladed rotor (low solidity) peaks at higher FM
- Peak FM occurs at a lower  $C_T/\sigma$  for 6-bladed rotor for given collective range



# Results: Low Solidity



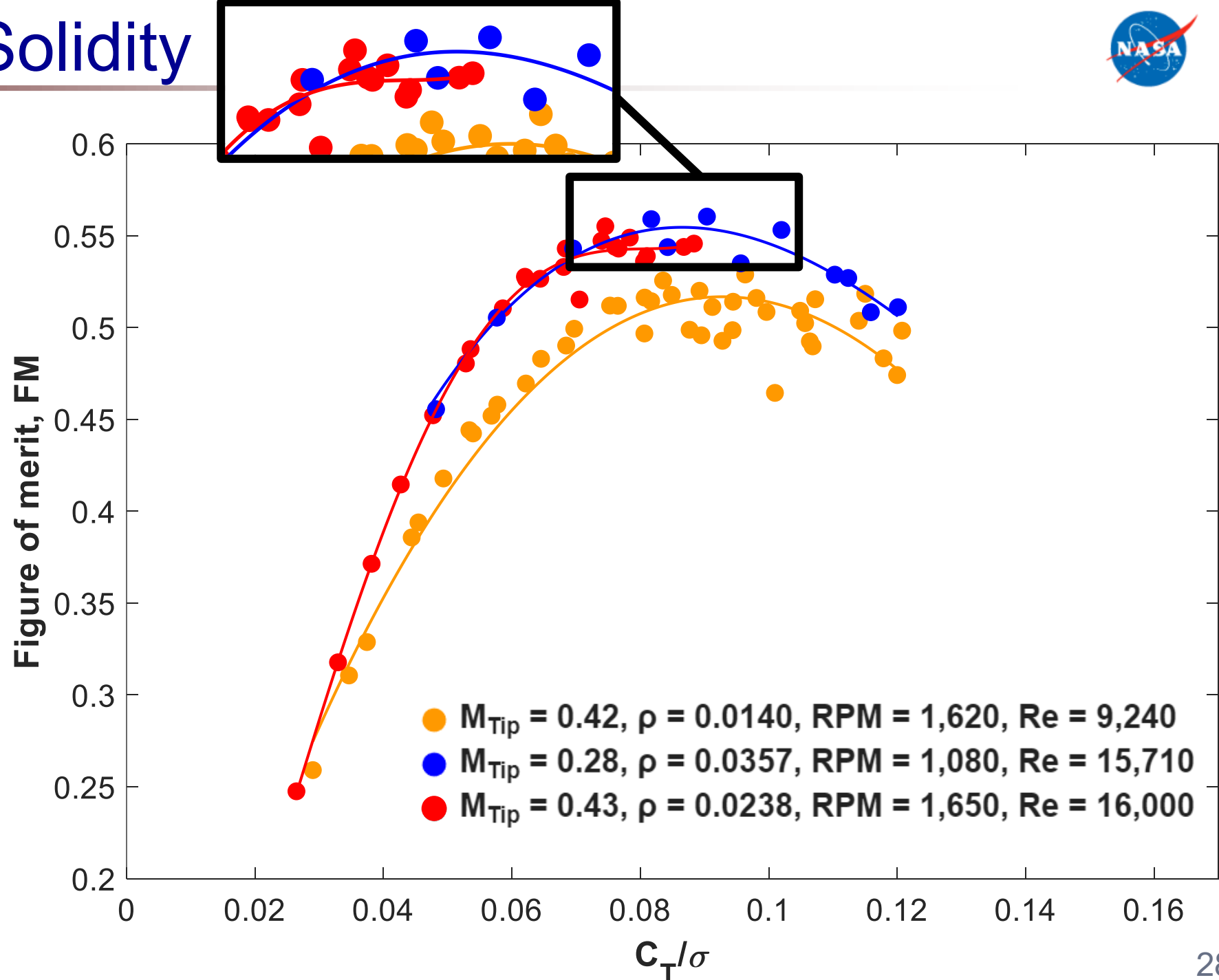
- FM increases with increase in Reynolds number
- Similar peak FM at Re of **19,850** and **22,400**



# Results: High Solidity



- FM increases with increase in Reynolds number
- Further investigation underway for large scatter at  $Re = 9,239$
- Peak figure of merit occurs at 0.56 at 0.09  $C_T/\sigma$  at  $Re = 15,707$
- Increased efficiency with increased density



# Summary and Conclusions



- HST campaign performed in the NASA JPL 25-ft Space Simulator for a low (3-bladed) and high solidity (6-bladed) rotor
- More thrust capability with increase in solidity (number of blades) for same collective
- Increase in solidity therefore increase in profile power
- Peak FM occurs at a lower  $C_T / \sigma$  for 6-bladed rotor for given collective range compared to 3-bladed rotor
- Further investigation of use of high solidity rotors is underway to understand discrepancies from current predictions

**Results will aid in future Mars rotorcraft development by providing data for validation efforts**

# Acknowledgments

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- NASA Ames Aeromechanics Office
- Ingenuity Mars Helicopter Team
- High Solidity Test Team
- Work was paid for by a combination of the Mars Exploration Program and SVTT

Portions of this research were carried out at the Jet Propulsion Laboratory, California Institute of Technology, under a contract with the National Aeronautics and Space Administration (80NM0018D0004).

Questions?



