

Updates to NASA Urban Air Mobility Reference Vehicles Incorporating Recent Technology, Policy, and Economic Developments

Christopher Silva Conceptual Design Tech Lead and Senior Technical Advisor NASA Revolutionary Vertical Lift Technology Project

> VFS Electric VTOL Symposium Santa Clara, California 6-8 February 2024

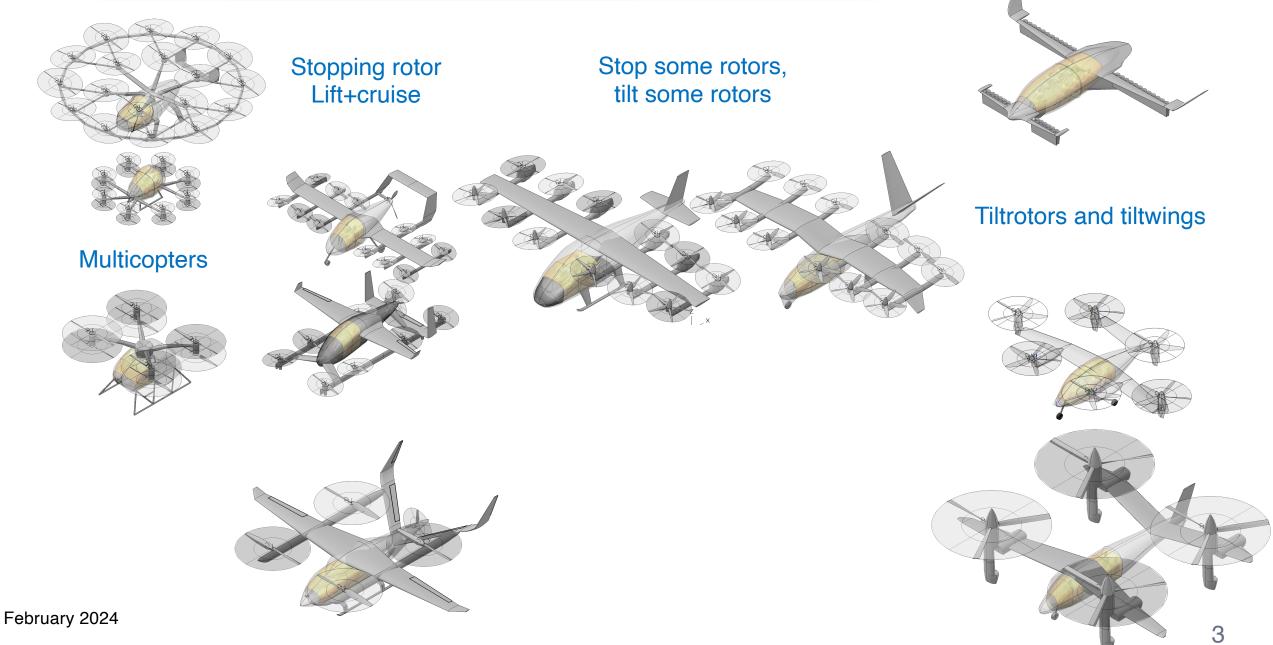


Aeromechanics Branch - NASA Ames Research Center



We observe very diverse VTOL vehicle solutions



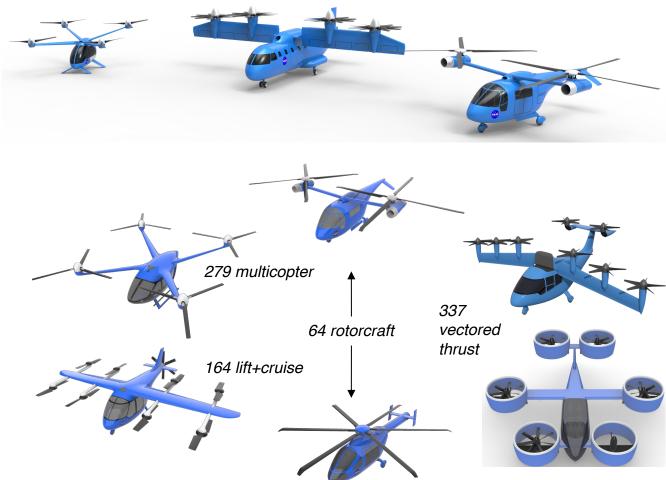


Why we designed the NASA reference vehicles

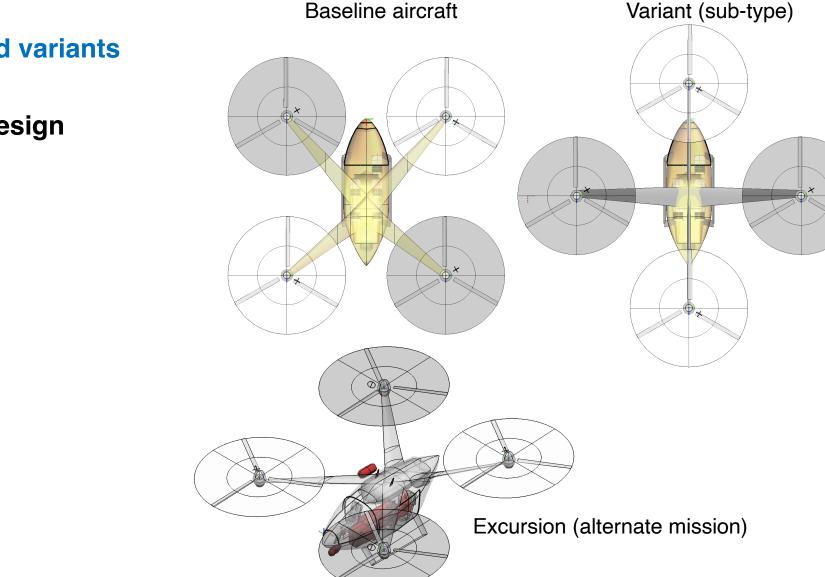


Vehicle model inputs and outputs publicly available

- Discussions can be quantitative
- Demonstration cases for training
- Features representative of vehicles
- Missions and design conditions
- Margins and reliability requirements
- Focus and guide government research
 - Enable contracted work to be published
 - Assess technology payoff
 - Guide tool development
 - Scope validation tests
- No plan or desire to build the vehicles
 - But these are not cartoons







- Baseline, excursions, and variants
- Reports
- NDARC design and off-design
- Geometry
- Comprehensive Analysis
- Structures
- Flight Dynamics



Baseline, excursions, and variants	Papers and journal articles	NASA publications
Reports	Concept Vehicles for VTOL Air Taxi Operations	NASA/TM-20210017971
NDARC design and off-design	Wayne Johnson Christopher Silva Eduardo Solis NASA Ames Research Center Science & Technology Corp. Moffert Field, California Moffert Field, California wayne.johnson@nasa.gov christopher.silva@nasa.gov	NASA
Geometry	ABSTRACT Concept vehicles are presented for air taxi operations, also known as urban air mobility or on-demand mobility applications. Considering the design-space dimensions of payload (passengers and pilot), range, aircraft tyre, and propulsion system. three aircraft are designed: a single-assenger (250-b)	Design of a Tiltwing Concept Vehicle for Urban
Comprehensive Analysis	range, atteint type, and population system, mere atteint are usigned, at single-passengel (20-10) payload), 50-nm range quadrotow with lederic propulsion; as it-passenger (200-10) payload), 4s:0 = 200-nm range side-by-side helicopter with hybrid propulsion; and a fifteen-passenger (3000-1b) payload), 8s:50 = 400-nm range titting with turbe-clettic propulsion. These concept vehicles are intended to focus and guide NASA research activities in support of aircraft development for emerging availation markets; in particular YTOL are lark as present and as are discussed, llustrated by	Air Mobility
Structures	results from the design of the concept vehicles. to explore a range of aircraft types, propulsion system INTRODUCTION types, and size, and to examine sensitivities to trades of	Siena K. S. Whiteside, Beau P. Pollard, Kevin R. Antcliff, Nikolas S. Zawodny, and Xiaofan Fei Langley Research Center, Hampton, Virginia
Flight Dynamics	Urban air taxi operations, also known as urban air mobility or on-demand mobility applications, are enabled by vertical take-off and landing (VTOL) capability, power and energy requirements are minimized by using low diak- loading rotors, and short range requirements permit consideration of non-traditional propulsion concepts. The community of innovation has recognized that technology advances in structures, automation and control, energy generation-sorrage-utilization, and tools for design and analysis, coupled with pressures of resource availability rebices that can be used to focus and guide NASA research activities in support of aircraft development for emerging avaiant markets, in particular VTOL air taxi	Christopher Silva Ames Research Center, Moffett Field, California Glenn L. Medina Universities Space Research Association, Hampton, Virginia
	operations. To meet this objective, the designs are carried far enough to identify crucial technologies and research requirements, Presented at the AHS Technical Conference on Aeromechanic Design for Tandormative Vertical Flight, San Francisco, CA, January 16-19, 2018. This is a work of the U.S. Government and is not subject to copyright protection. 4	June 2021

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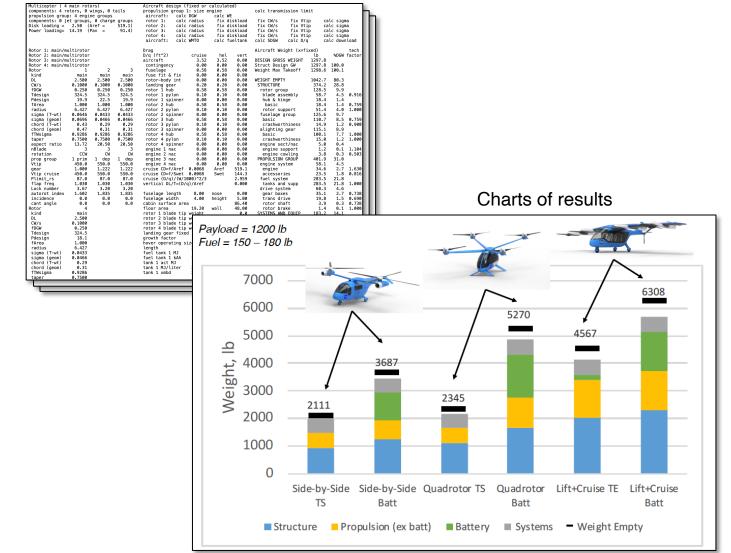
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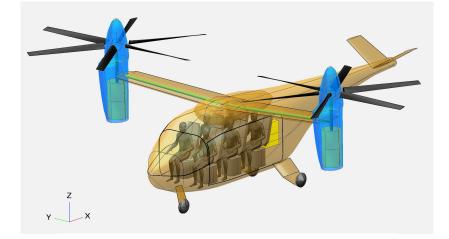
NDARC job outputs (text)



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OpenVSP for initial design



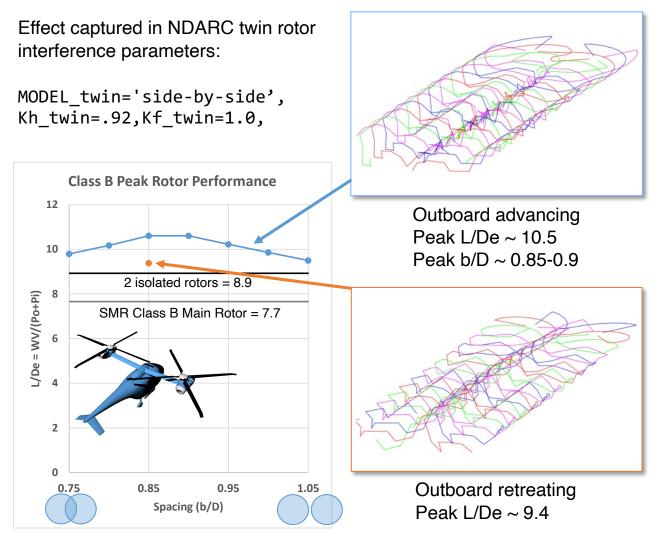
Watertight, smoothed geometry for CFD

Transformative Vertical Flight 2024 11th Annual Electric VTOL Symposium 6th Decennial VFS Aeromechanics Specialists' Conference Feb. 6-8, 2024 | Santa Clara, CA, USA

Rendered aircraft for communication and engagement

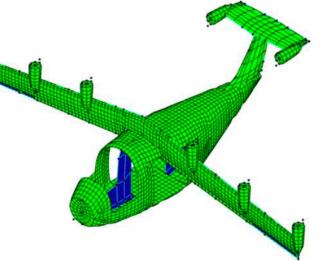


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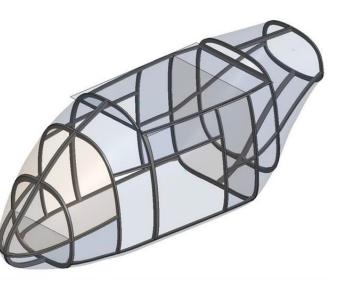




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Tiltwing NASTRAN model



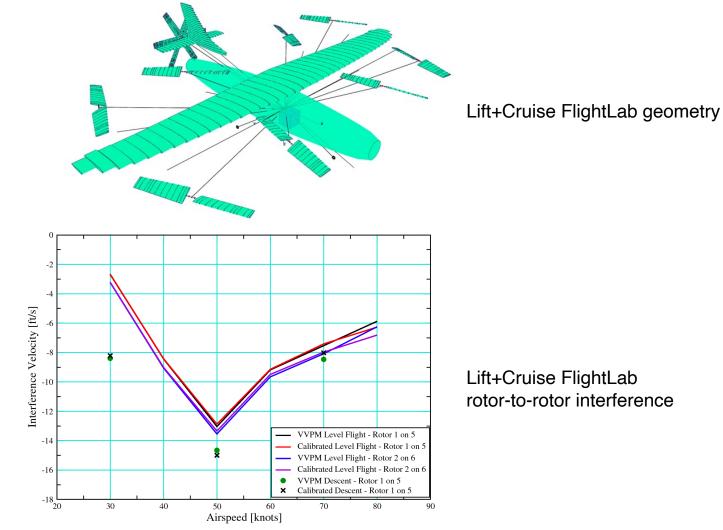


Lift+Cruise cabin crash test article structural components





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Reference vehicles for UAM: baselines & some trades we have performed Quadrotor "Air taxi" "UAM"

6.15

Collective+trim,

monocyclic

Direct, gear, xshaft

Turboshaft, turboelectric,

battery

6

Rotor y/R

Rotation

Turboshaft, parallel

hybrid, battery

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Occupants

Propulsion

Rotors

1, 2, 4, **6**

RPM, collective

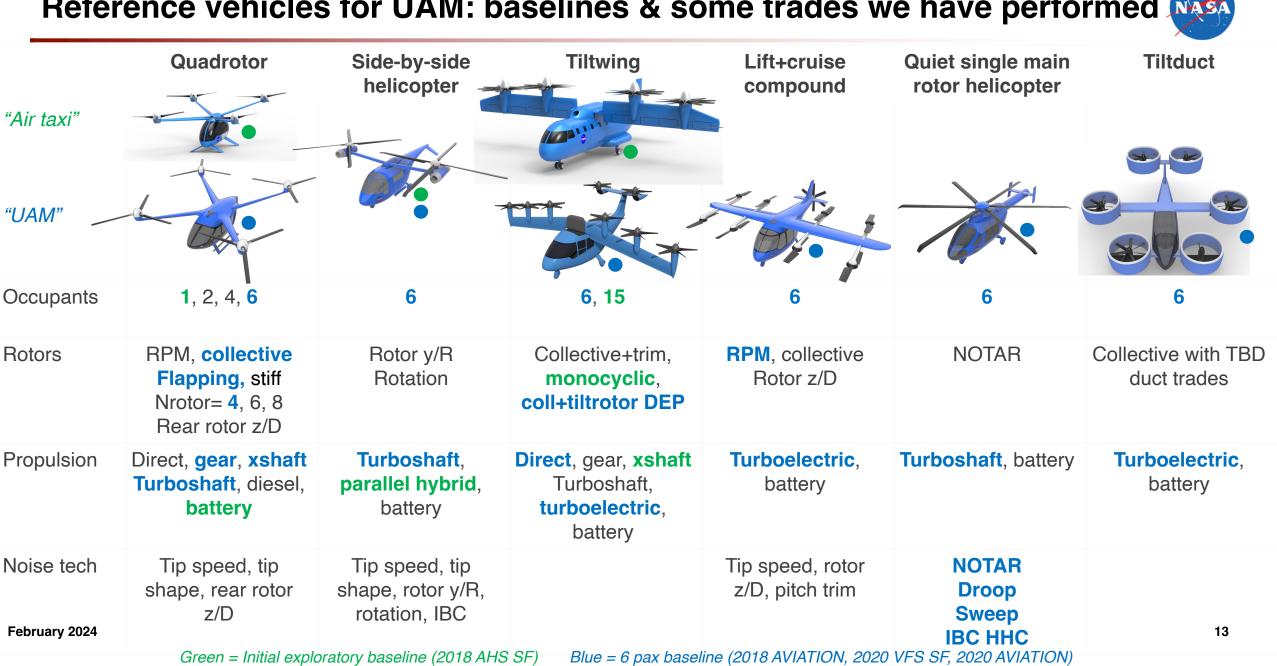
Flapping, stiff

Nrotor= 4, 6, 8Rear rotor z/D

Direct, gear, xshaft Turboshaft, diesel,

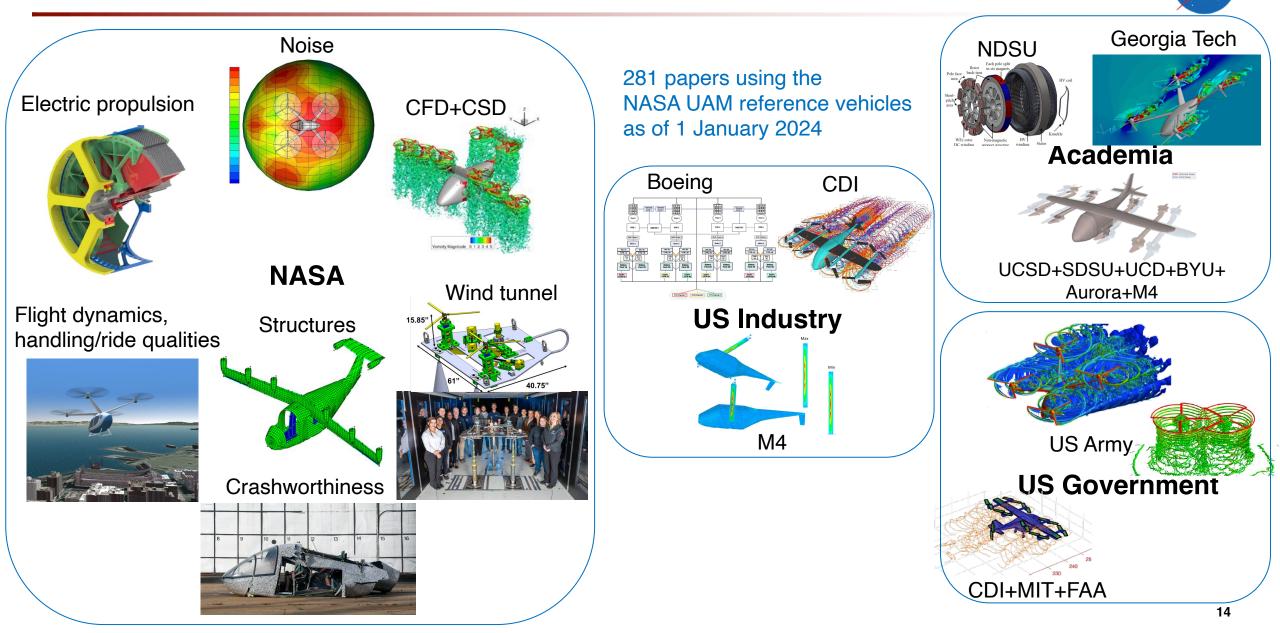
battery

Green = Initial exploratory baseline (2018 AHS SF) Blue = 6 pax baseline (2018 AVIATION, 2020 VFS SF, 2020 AVIATION)

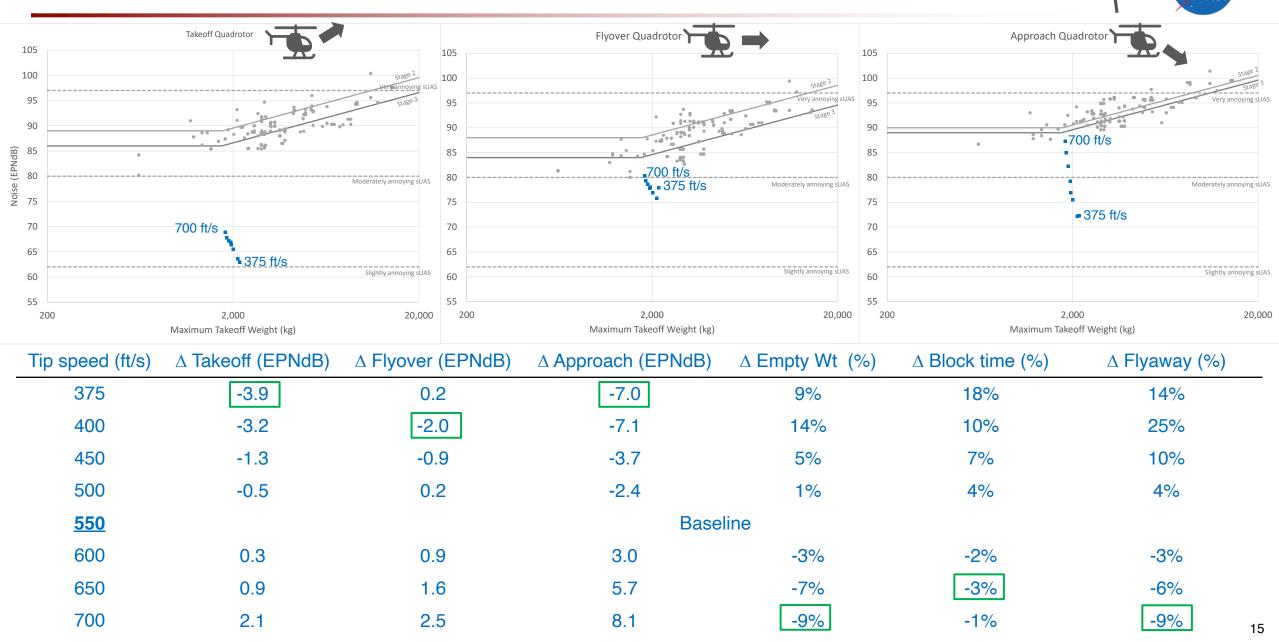


Reference vehicles for UAM: baselines & some trades we have performed

What have people been (publicly) doing with the models?

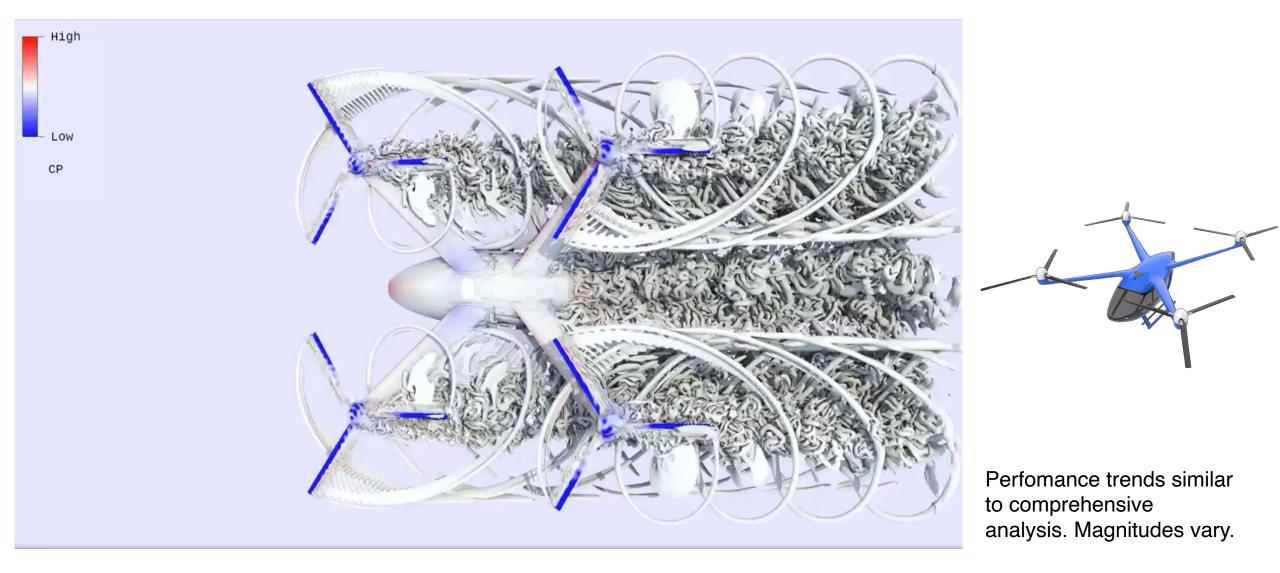


Tip speed: Quadrotor most (noise) improvement in approach



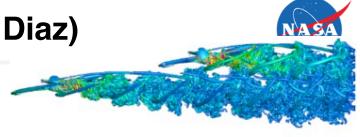
Loose-coupled CFD: Can we minimize bad interactions? (Ventura Diaz)



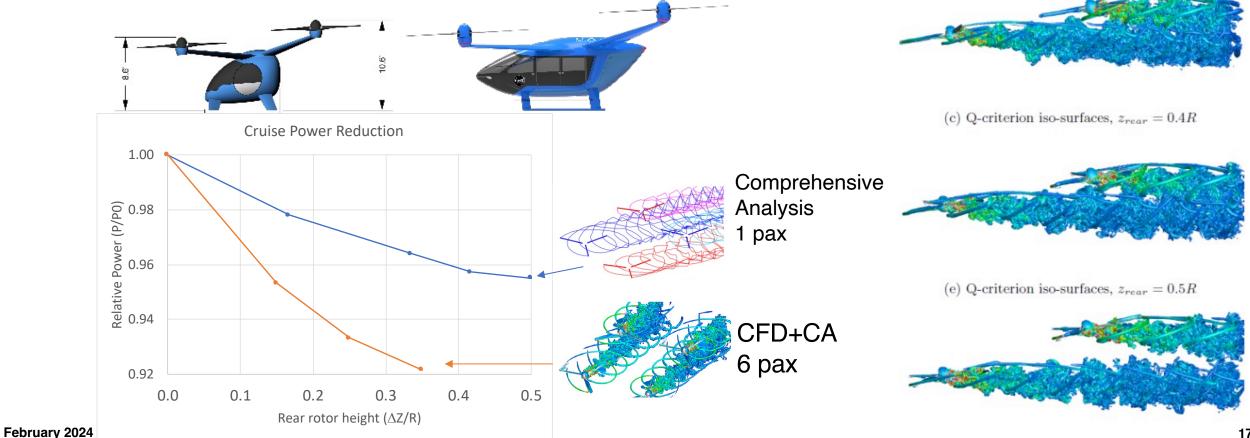


More detailed look into rotor-rotor interactions (Ventura Diaz)

- Wakes impact downstream rotors .
- Mid-fidelity tools predict the cost / benefit •
- High-fidelity to confirm effects (or not!) ٠



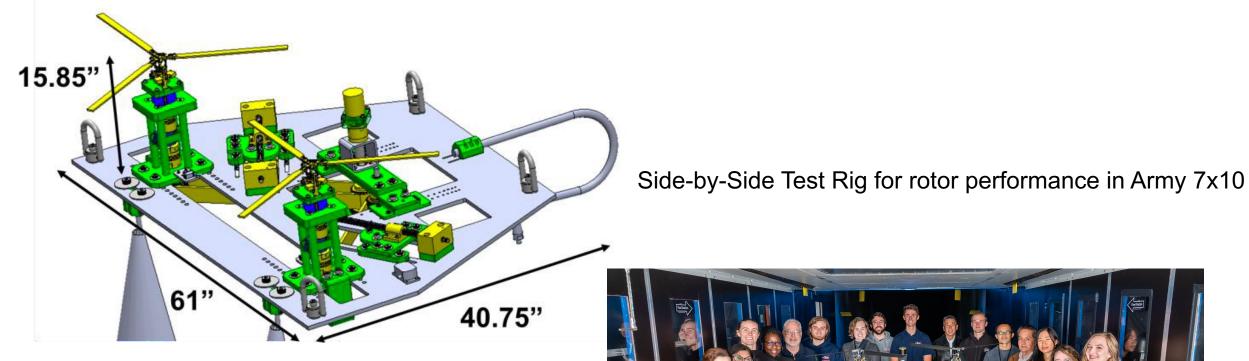


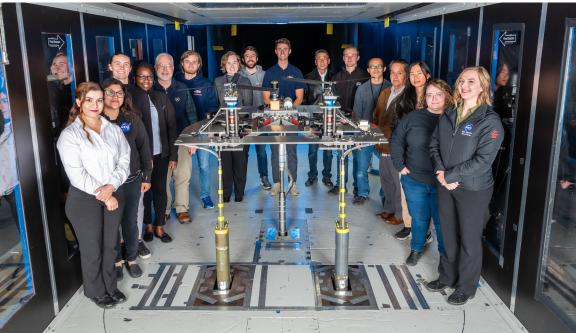


If you can predict productive interference, might as well measure it



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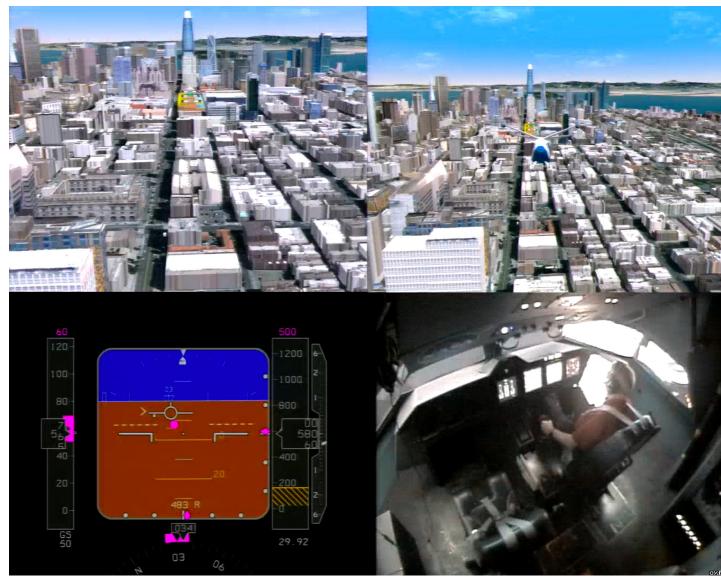




VMS testing and handling qualities analysis



- RPM sluggish and sloppy if motors not capable of at least 2x the torque required for steady operation
 - Pilots really dislike sluggish RPM
 - Passengers dislike sloppy RPM
 - Motor sizing needs to be updated
- Small rotors for reasonable RPM control
 - This is one argument for Distributed Electric Propulsion (DEP)
 - Somewhere around 5 ft radius probably the cutoff, but not sure yet



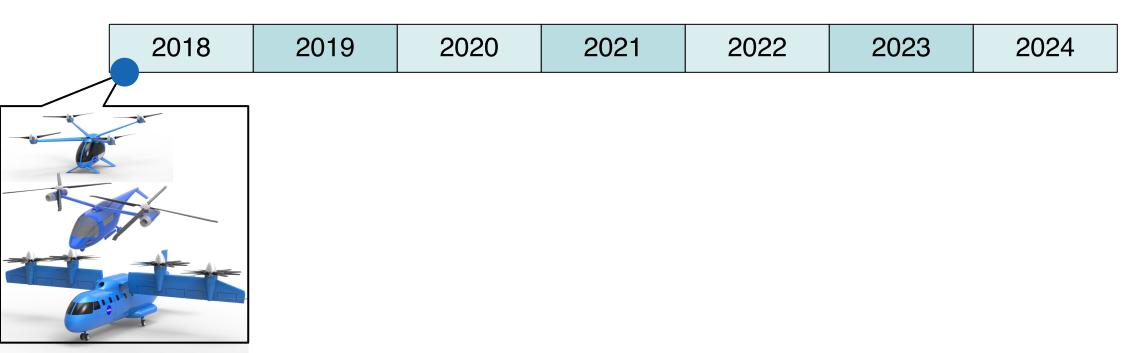






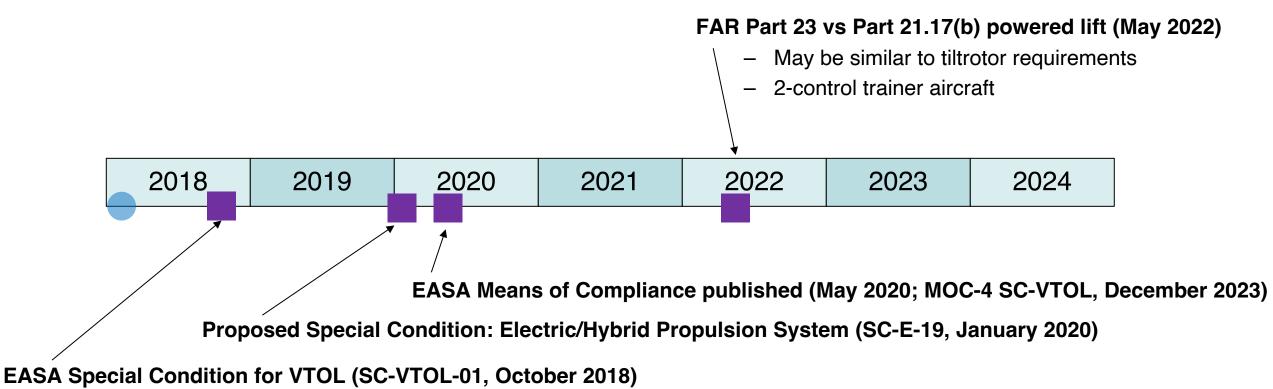
The UAM landscape was a bit different in early 2018





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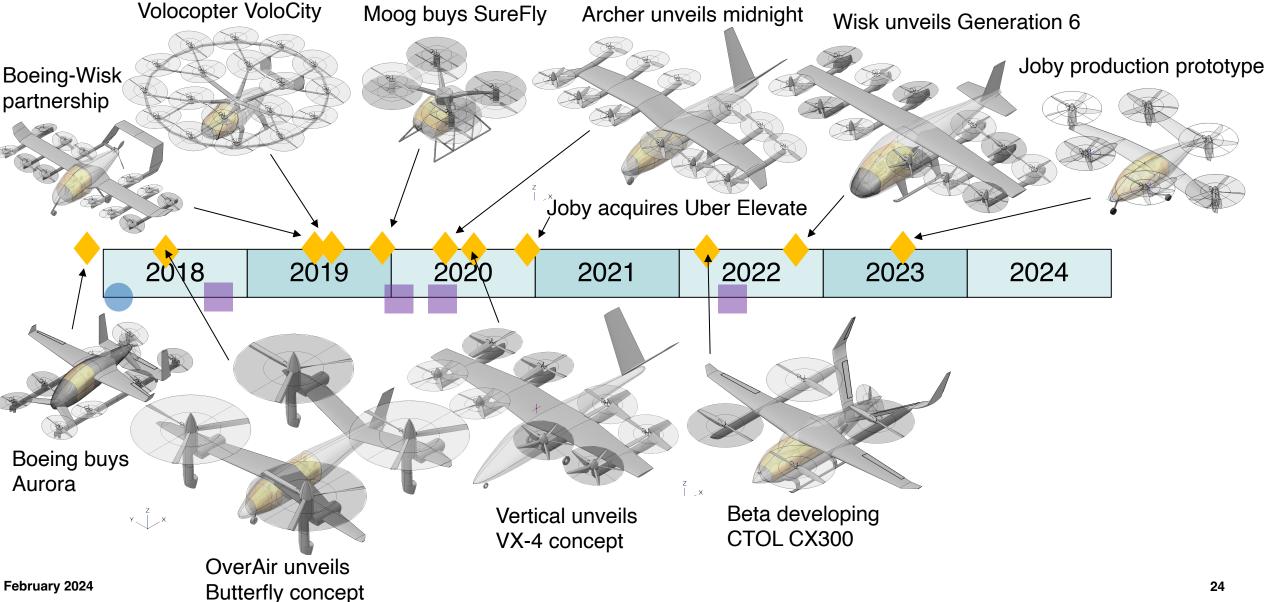


- Allowing operation into and at low altitudes above European urban areas
- No single point of failure in rotating parts
- 10⁻⁹ catastrophic failures per flight hour over populated areas

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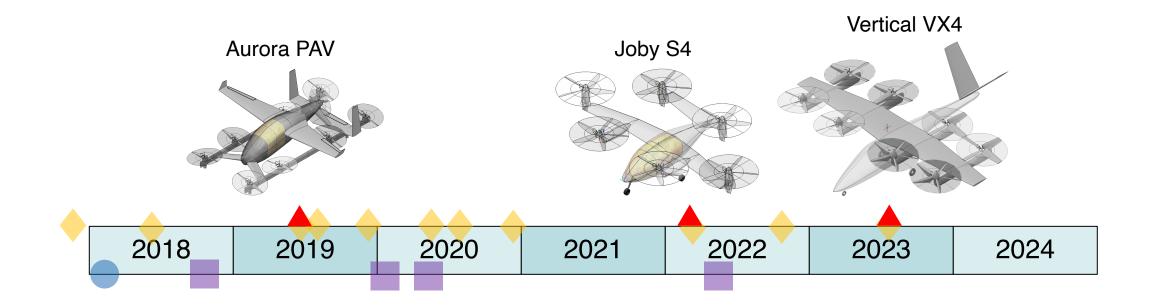
(Just a few of the many) New companies and changed vehicles





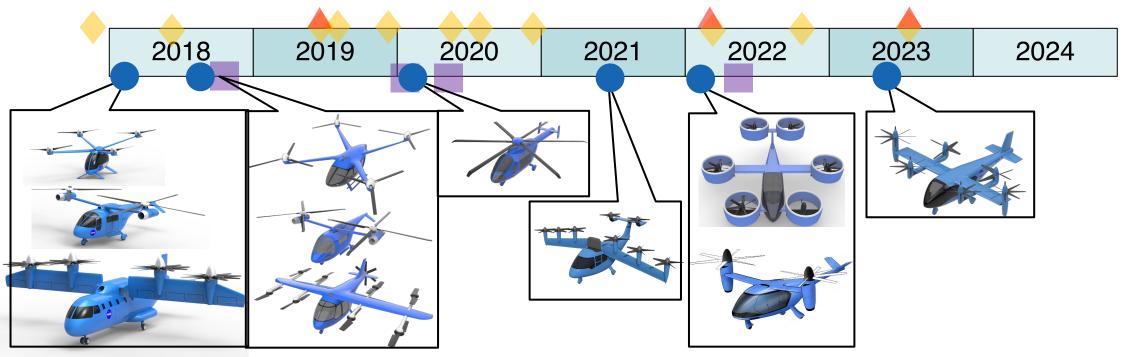
Crashes in full-scale flight test



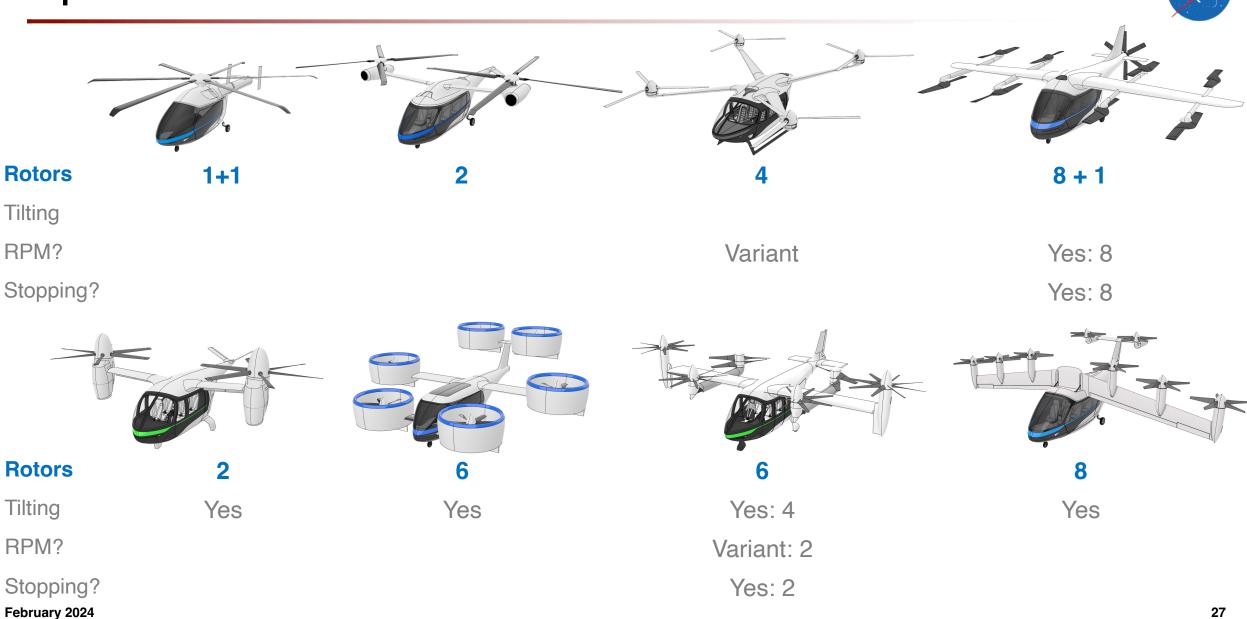


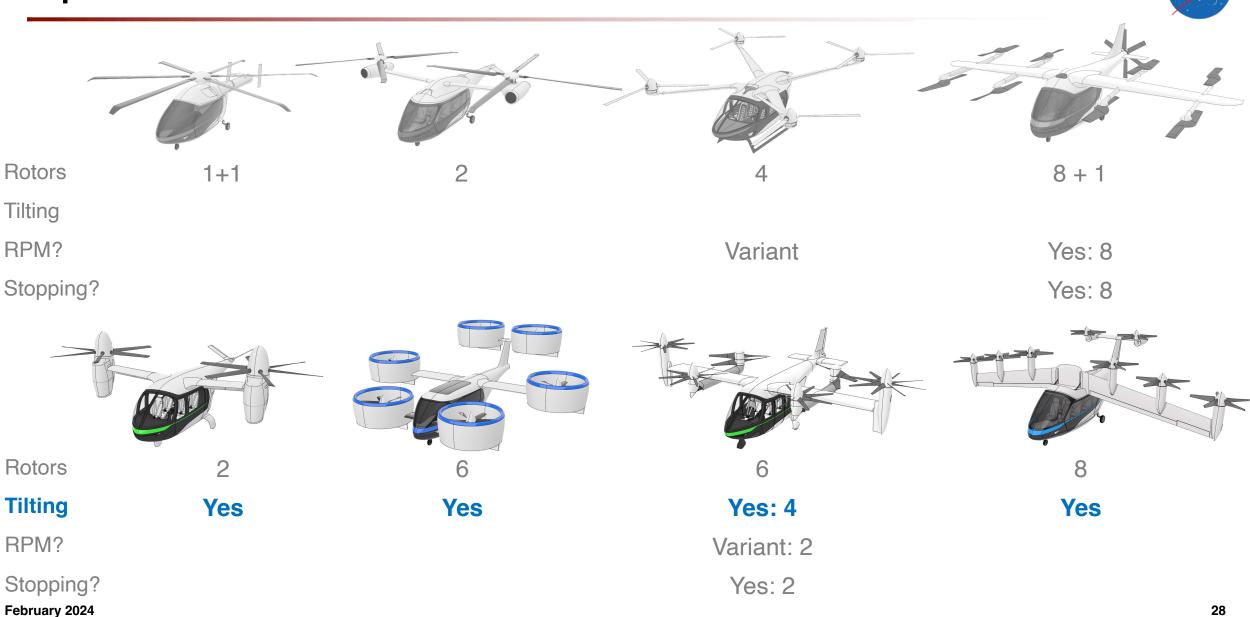
Incremental updates and additions to NASA UAM Reference Vehicles

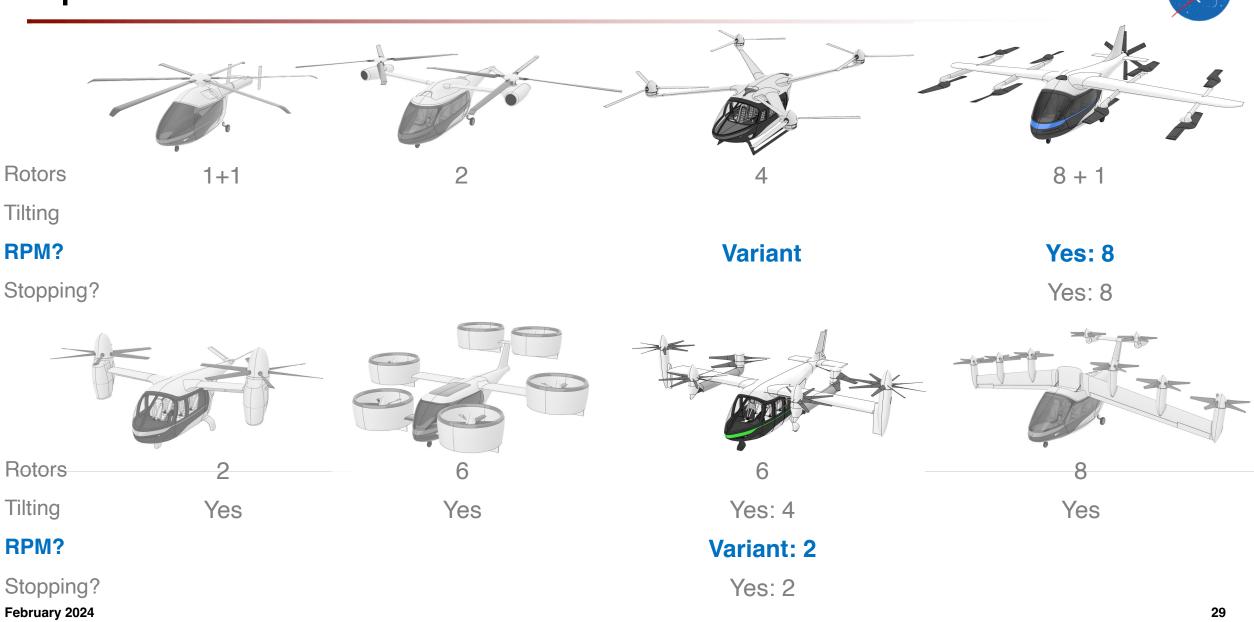


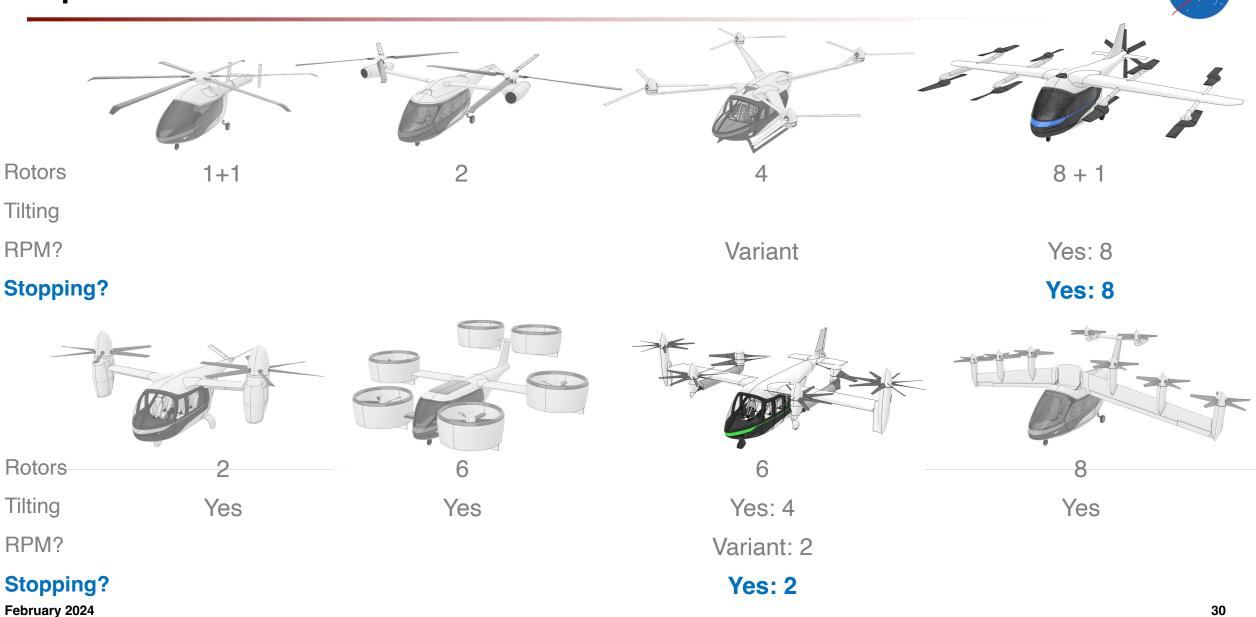


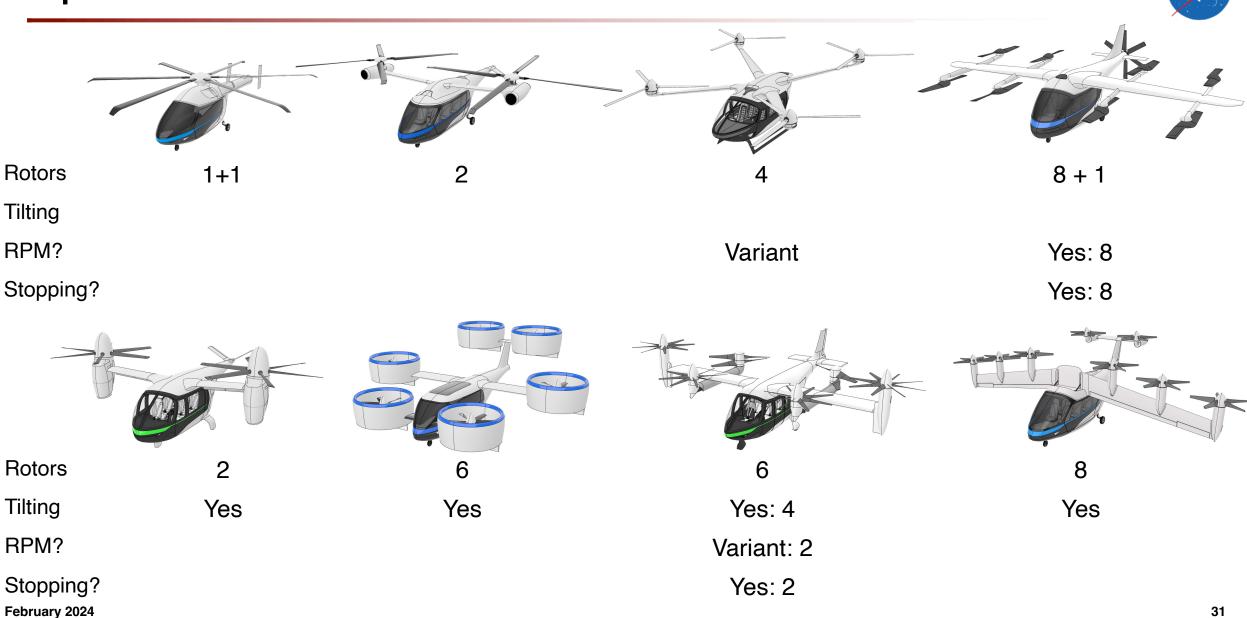
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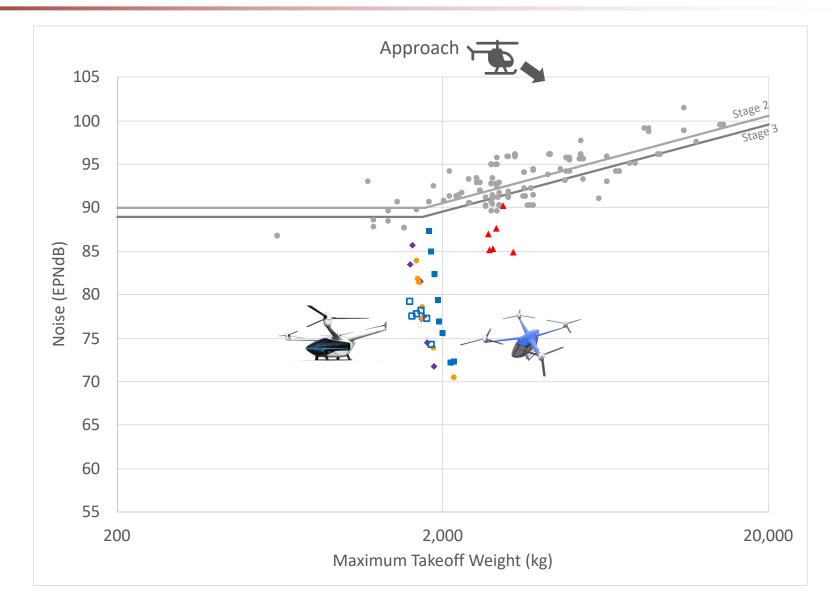






Part 36H Certification Approach Noise Prediction

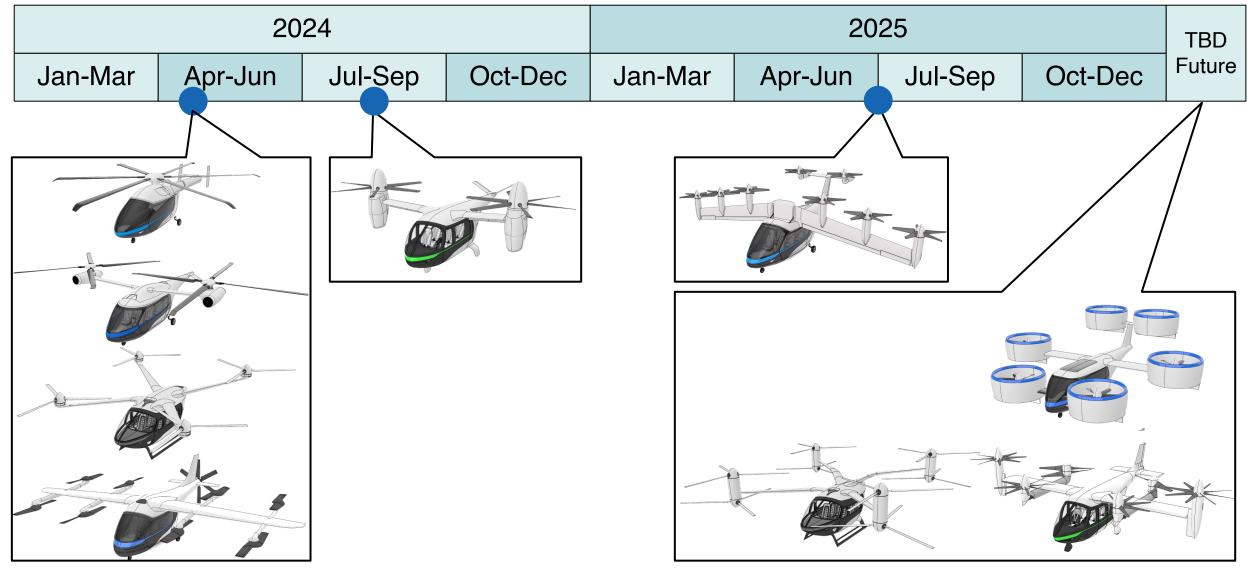






When will updated UAM Reference Vehicle models be available?







- NDARC website NDARC Users
 - https://rotorcraft.arc.nasa.gov/ndarc/
 - Request NDARC: https://software.nasa.gov/software/ARC-16265-1
- Langley Research Center Systems Analysis and Concepts Directorate- Aeronautics Systems Analysis Branch (LaRC SACD ASAB) – Publicly available
 - https://sacd.larc.nasa.gov/uam-refs/
- NASA Technical Reports Server Publicly available (reports only)
 - https://ntrs.nasa.gov

